Hashing

What is it?

A form of narcotic intake?

A side order for your eggs?

A combination of the two?

Problem

- RT&T is a large phone company, and they want to provide enhanced caller ID capability:
 - given a phone number, return the caller's name
 - phone numbers are in the range 0 to $R = 10^{10} 1$
 - n is the number of phone numbers used
 - want to do this as efficiently as possible
- We know two ways to design this dictionary:
 - a *balanced search tree* (AVL, red-black) or a skiplist with the phone number as the key has O(log *n*) query time and O(*n*) space --- good space usage and search time, but can we reduce the search time to constant?
 - a *bucket array* indexed by the phone number has optimal O(1) query time, but there is a huge amount of wasted space: O(n + R)

(null)		(null)	•••	Roberto	•••	(null)
000-000-00	000 0)00-000-0001	••••	401-863-7639	(999-999-9999

Another Solution

- A *Hash Table* is an alternative solution with O(1) expected query time and O(n + N) space, where *N* is the size of the table
- Like an array, but with a function to map the large range of keys into a smaller one
 - e.g., take the original key, *mod* the size of the table, and use that as an index
- Insert item (401-863-7639, Roberto) into a table of size 5
 - 4018637639 mod 5 = 4, so item (401-863-7639, Roberto) is stored in slot 4 of the table

				401- 863-7639 Roberto
0	1	2	3	5

- A lookup uses the same process: map the key to an index, then check the array cell at that index
- Insert (401-863-9350, Andy)
- And insert (401-863-2234, Devin). We have a *collision*!

Collision Resolution

- How to deal with two keys which map to the same cell of the array?
- Use *chaining*
 - Set up *lists* of items with the same index



- The expected, search/insertion/removal time is O(*n*/*N*), provided the indices are uniformly distributed
- The performance of the data structure can be finetuned by changing the table size *N*

From Keys to Indices

- The mapping of keys to indices of a hash table is called a *hash function*
- A hash function is usually the composition of two maps:
 - *hash code map*: key \rightarrow integer
 - *compression map*: integer $\rightarrow [0, N-1]$
- An essential requirement of the hash function is to map equal keys to equal indices
- A "good" hash function minimizes the probability of collisions
- Java provides a hashCode() method for the Object class, which typically returns the 32-bit memory address of the object.
- This default hash code would work poorly for Integer and String objects
- The hashCode() method should be suitably redefined by classes.

Popular Hash-Code Maps

- *Integer cast*: for numeric types with 32 bits or less, we can reinterpret the bits of the nuber as an int
- *Component sum*: for numeric types with more than 32 bits (e.g., long and double), we can add the 32-bit components.
- **Polynomial accumulation**: for strings of a natural language, combine the character values (ASCII or Unicode) $a_0a_1 \dots a_{n-1}$ by viewing them as the coefficients of a polynomial:

$$a_0 + a_1 x + \dots + x^{n-1} a_{n-1}$$

- The polynomial is computed with *Horner's rule*, ignoring overflows, at a fixed value *x*:

 $a_0 + x (a_1 + x (a_2 + \dots x (a_{n-2} + x a_{n-1}) \dots))$

- The choice x = 33, 37, 39, or 41 gives at most 6 collisions on a vocabulary of 50,000 English words
- Why is the component-sum hash code bad for strings?

Popular Compression Maps

- **Division**: $h(k) = |k| \mod N$
 - the choice $N = 2^k$ is bad because not all the bits are taken into account
 - the table size *N* is usually chosen as a prime number
 - certain patterns in the hash codes are propagated
- *Multiply, Add, and Divide* (MAD): $h(k) = |ak + b| \mod N$
 - eliminates patterns provided $a \mod N \neq 0$
 - same formula used in linear congruential (pseudo) random number generators

More on Collisions

- A key is mapped to an already occupied table location
 - what to do?!?
- Use a collision handling technique
- We've seen *Chaining*
- Can also use *Open Addressing*
 - Double Hashing
 - Linear Probing



Linear Probing

• If the current location is used, try the next table location

```
linear_probing_insert(K)
if (table is full) error
probe = h(K)
while (table[probe] occupied)
probe = (probe + 1) mod M
```

```
table[probe] = K
```

- Lookups walk along table until the key or an empty slot is found
- Uses less memory than chaining
 - don't have to store all those links
- Slower than chaining
 - may have to walk along table for a long way
- Deletion is more complex
 - either mark the deleted slot
 - or fill in the slot by shifting some elements down

Linear Probing Example

- $h(k) = k \mod 13$
- Insert keys:







Double Hashing

- Use two hash functions
- If M is prime, eventually will examine every position in the table

```
double_hash_insert(K)
if(table is full) error
```

```
probe = h1(K)
offset = h2(K)
```

```
while (table[probe] occupied)
probe = (probe + offset) mod M
```

table[probe] = K

- Many of same (dis)advantages as linear probing
- Distributes keys more uniformly than linear probing does

Double Hashing Example

- h1(K) = K mod 13 h2(K) = 8 - K mod 8
 - we want h2 to be an offset to add



Double Hashing Example (cont.) 18 32 59 31 4 5 6 9 10 11 12

Theoretical Results

- Let $\alpha = N/M$
 - the load factor: average number of keys per array index
- Analysis is probabilistic, rather than worst-case

Expected Number of Probes



Expected Number of Probes vs. Load Factor

