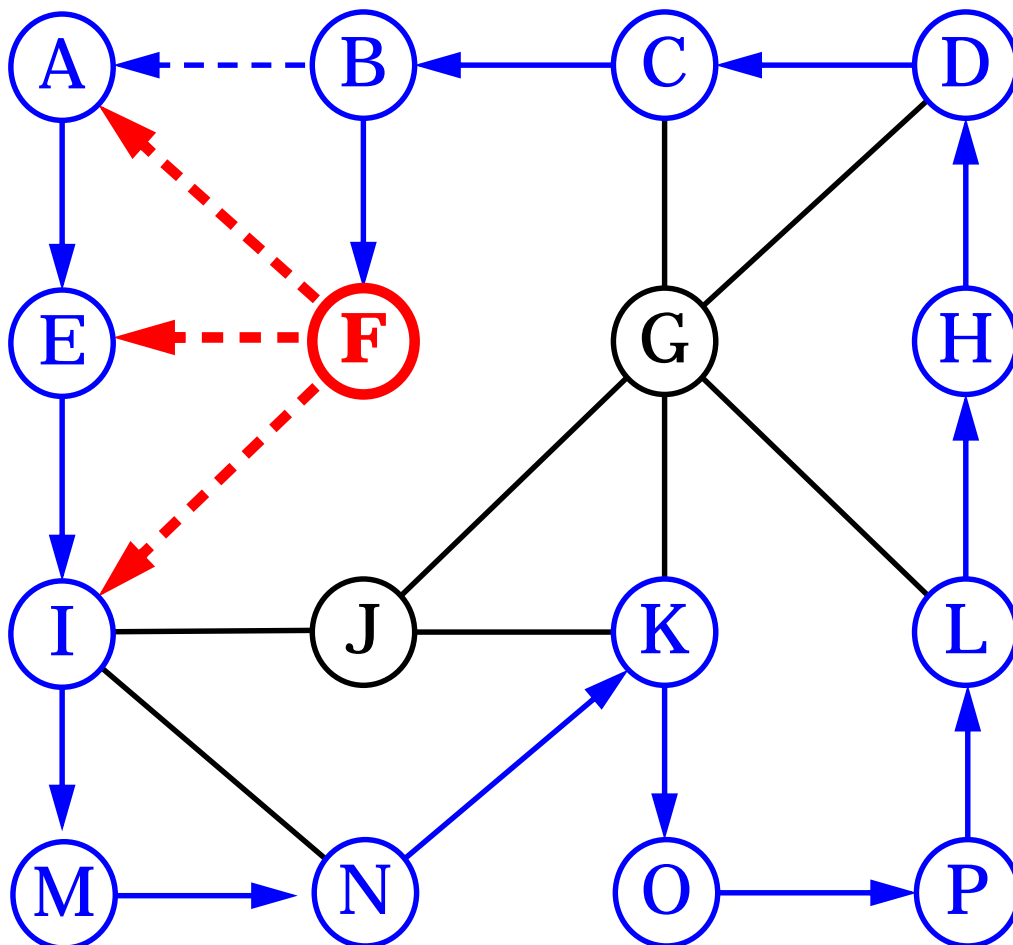


GRAPH TRAVERSALS

- Depth-First Search
- Breadth-First Search
- Template Method Pattern



Exploring a Labyrinth Without Getting Lost

- A **depth-first search (DFS)** in an undirected graph G is like wandering in a labyrinth with a string and a can of red paint without getting lost.
- We start at vertex s , tying the end of our string to the point and painting s “visited”. Next we label s as our current vertex called u .
- Now we travel along an arbitrary edge (u,v) .
- If edge (u,v) leads us to an already visited vertex v we return to u .
- If vertex v is unvisited, we unroll our string and move to v , paint v “visited”, set v as our current vertex, and repeat the previous steps.
- Eventually, we will get to a point where all incident edges on u lead to visited vertices. We then backtrack by unrolling our string to a previously visited vertex v . Then v becomes our current vertex and we repeat the previous steps.

Exploring a Labyrinth Without Getting Lost (cont.)

- Then, if we all incident edges on v lead to visited vertices, we backtrack as we did before. We continue to backtrack along the path we have traveled, finding and exploring unexplored edges, and repeating the procedure.
- When we backtrack to vertex s and there are no more unexplored edges incident on s , we have finished our **DFS** search.

Depth-First Search

Algorithm DFS(v);

Input: A vertex v in a graph

Output: A labeling of the edges as “discovery” edges and “backedges”

for each edge e incident on v **do**

if edge e is unexplored **then**

 let w be the other endpoint of e

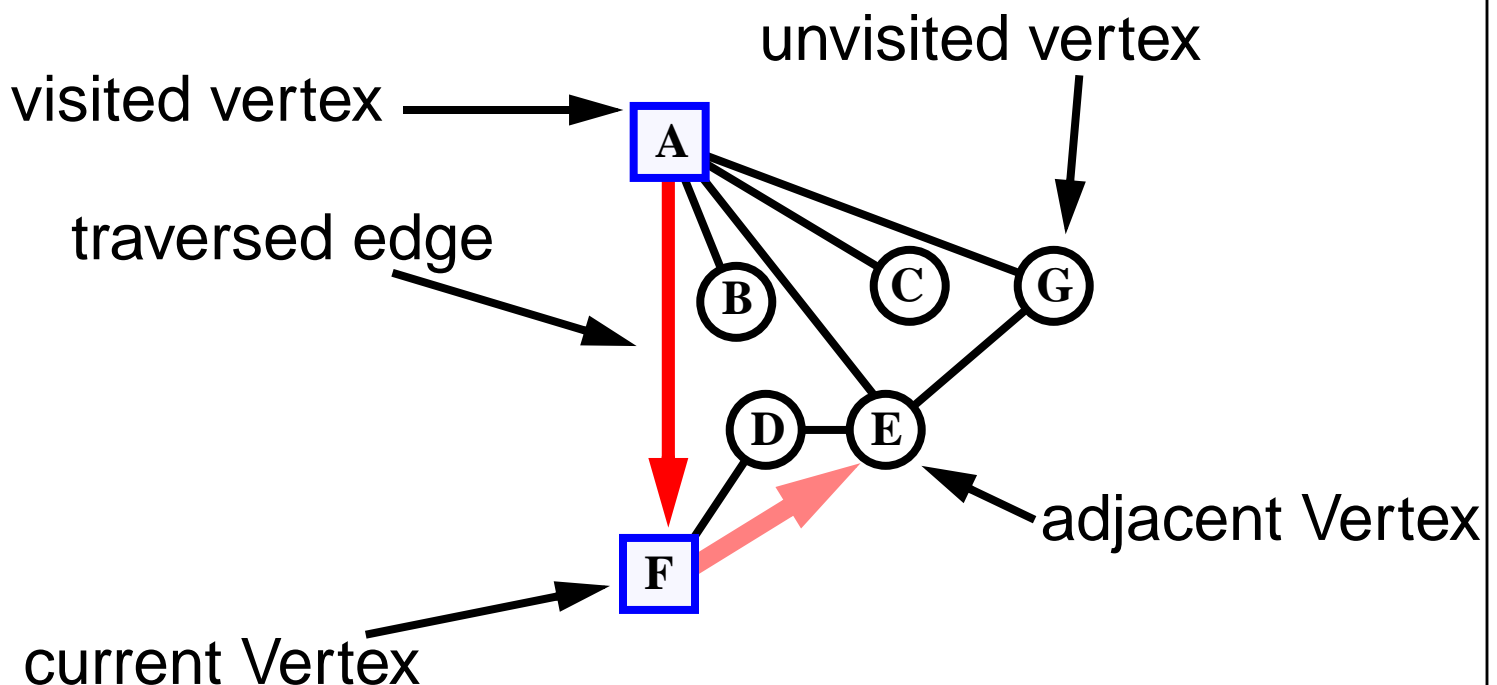
if vertex w is unexplored **then**

 label e as a discovery edge

 recursively call **DFS**(w)

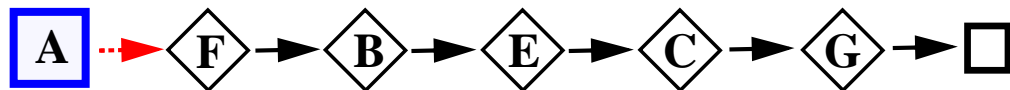
else

 label e as a backedge

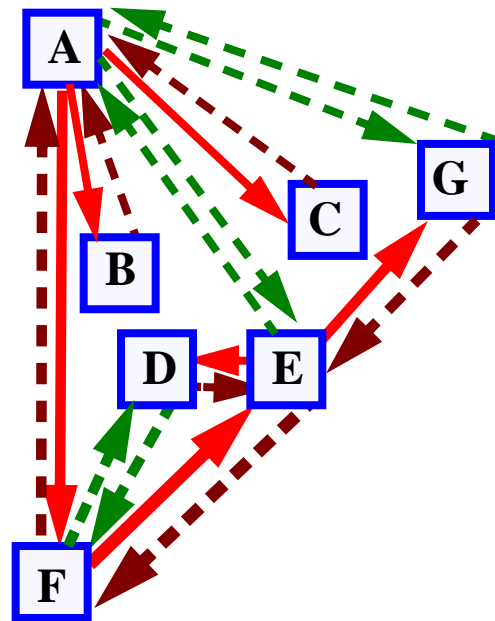
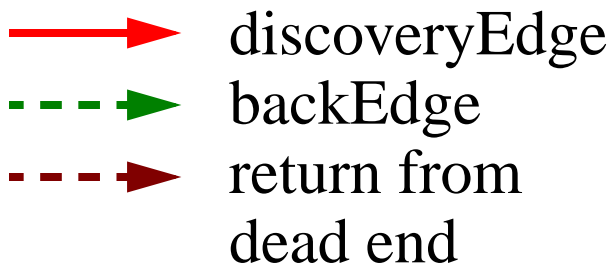


Determining Incident Edges

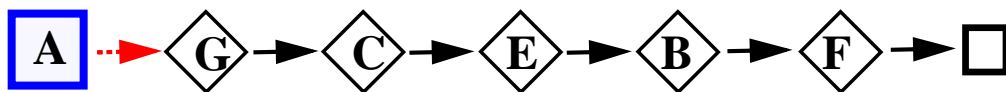
- DFS depends on how you obtain the incident edges.
- If we start at A and we examine the edge to F, then to B, then E, C, and finally G



The resulting graph is:

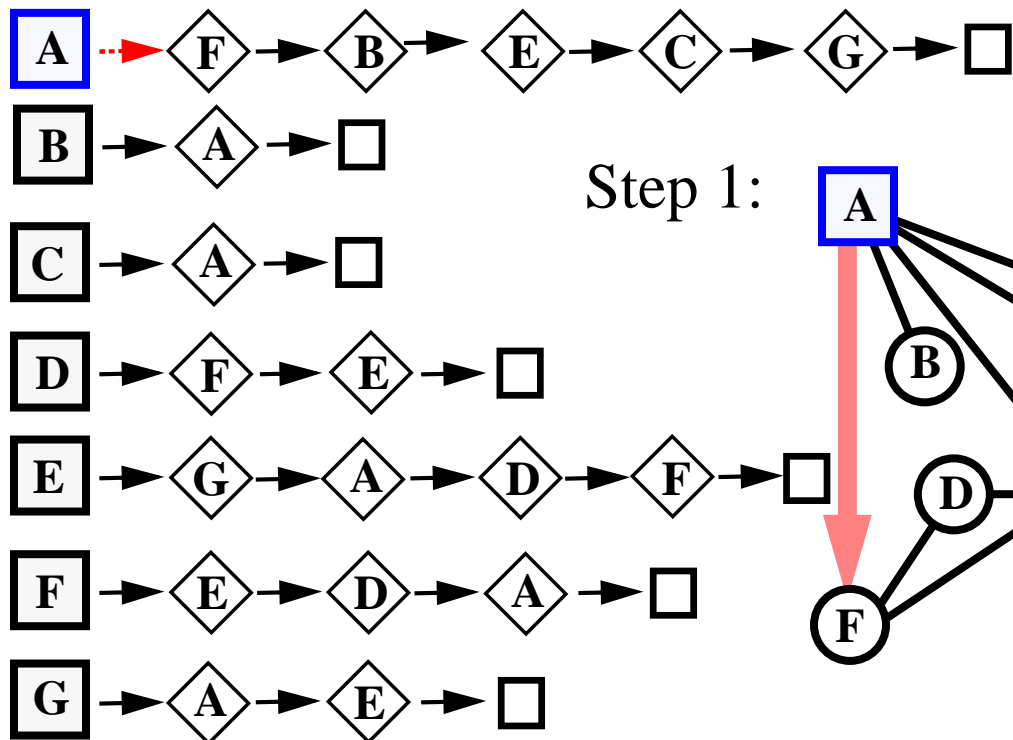


If we instead examine the tree starting at A and looking at F, the C, then E, B, and finally F,

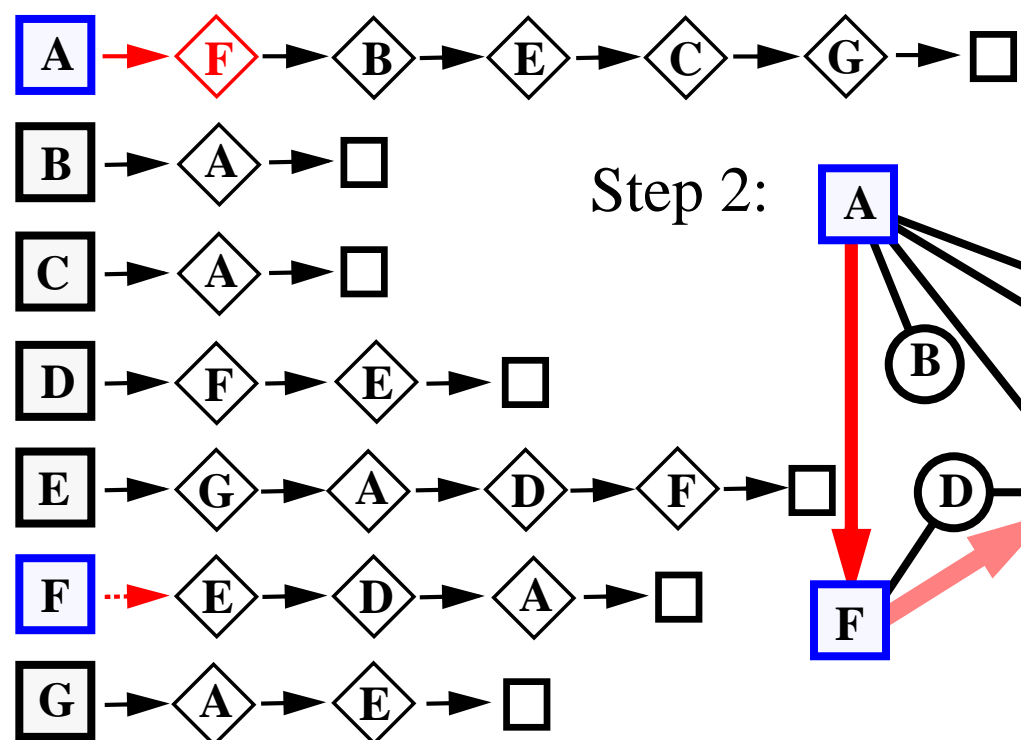
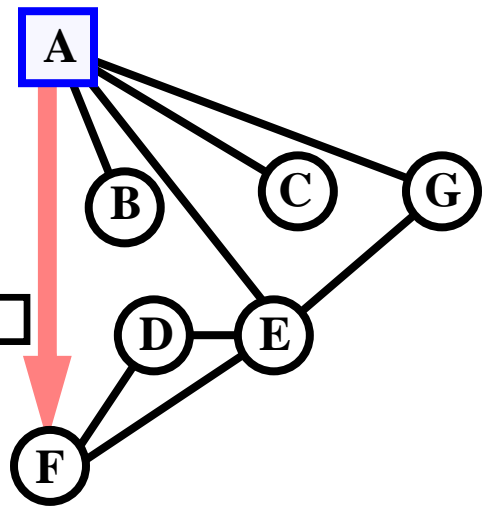


the resulting set of backEdges, discoveryEdges and recursion points is different.

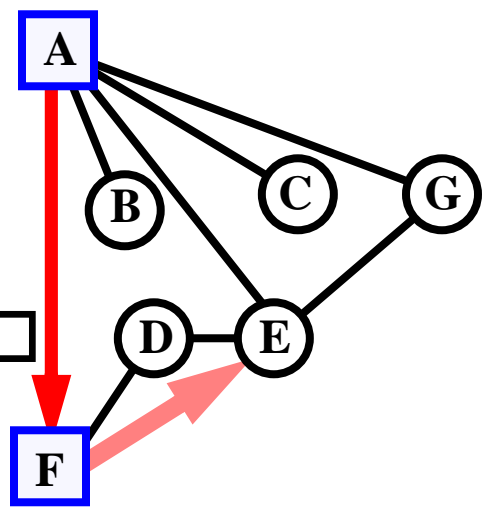
- Now an example of a DFS.

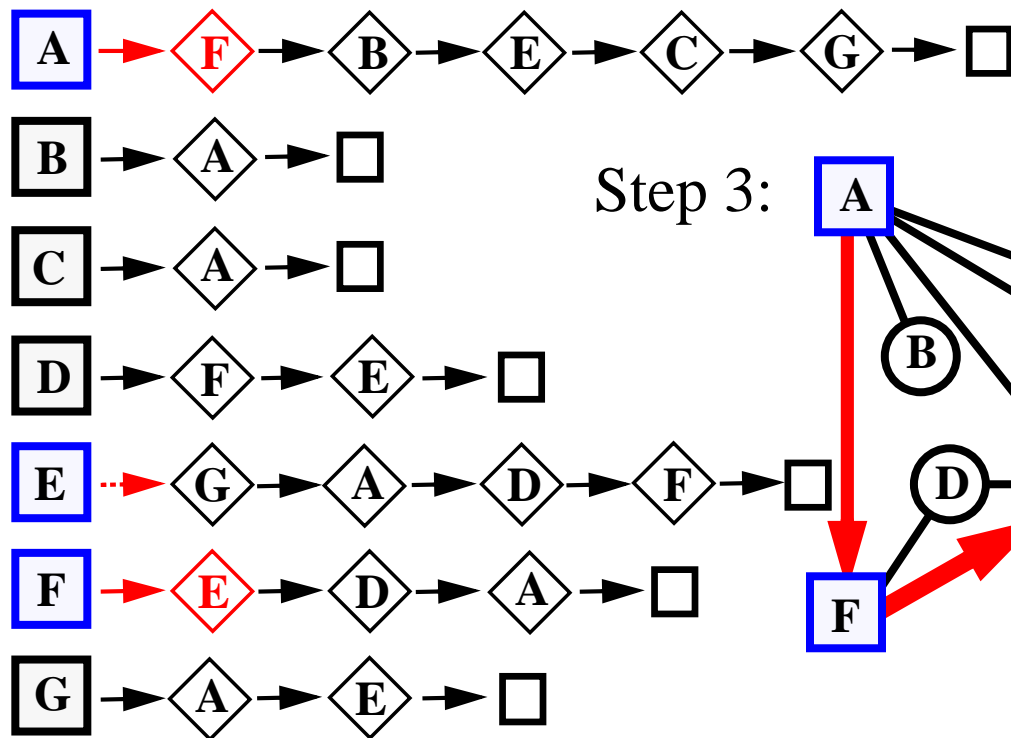


Step 1:

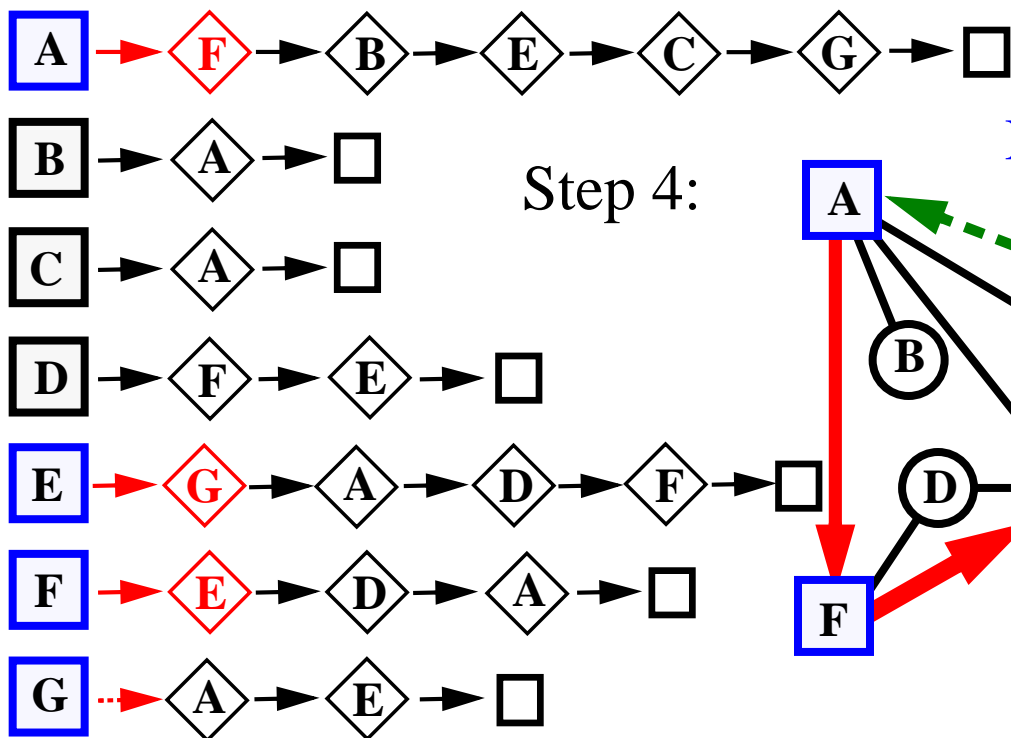
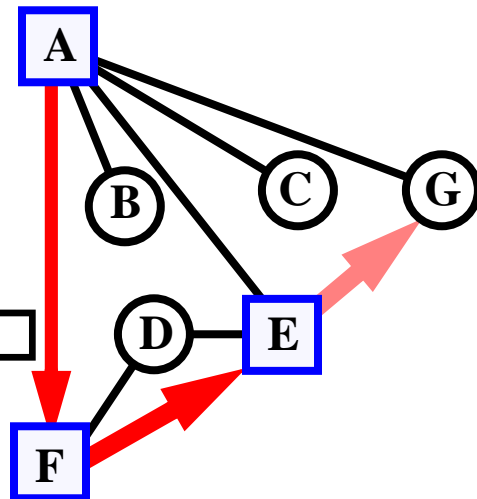


Step 2:

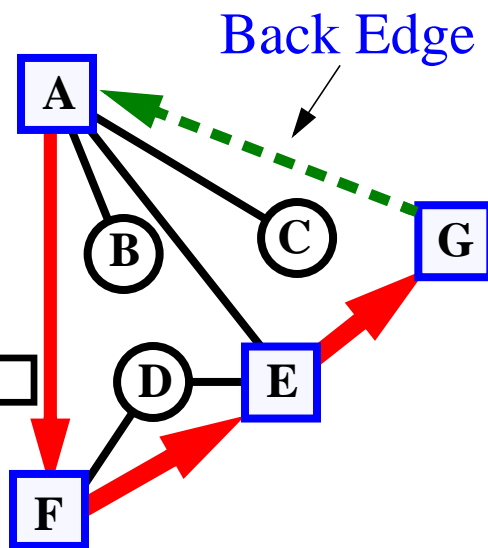


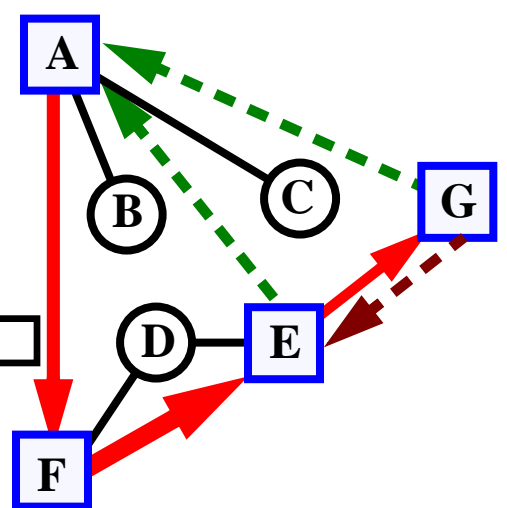
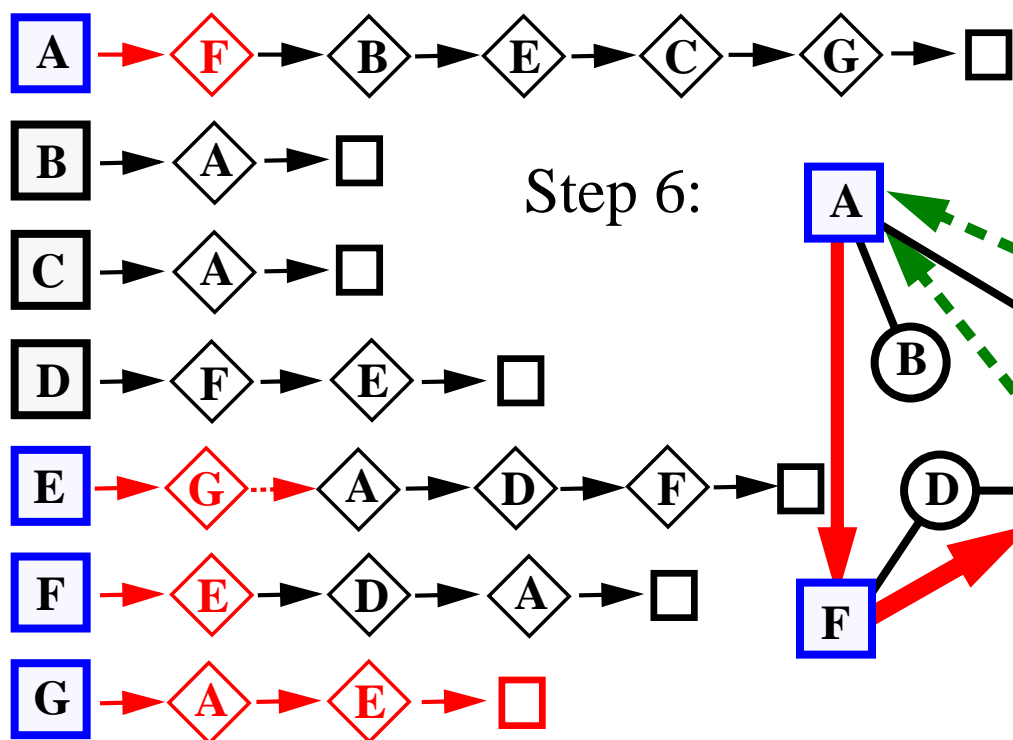
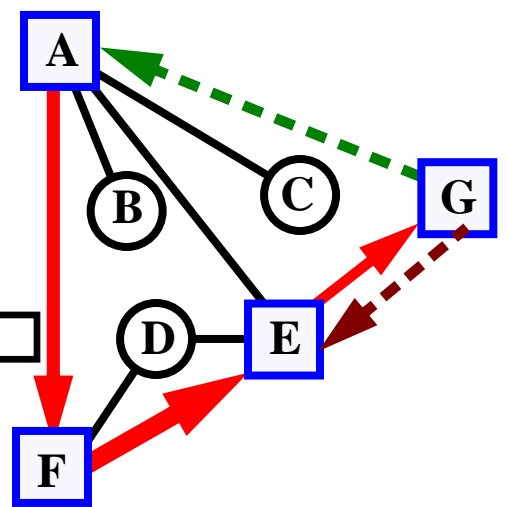
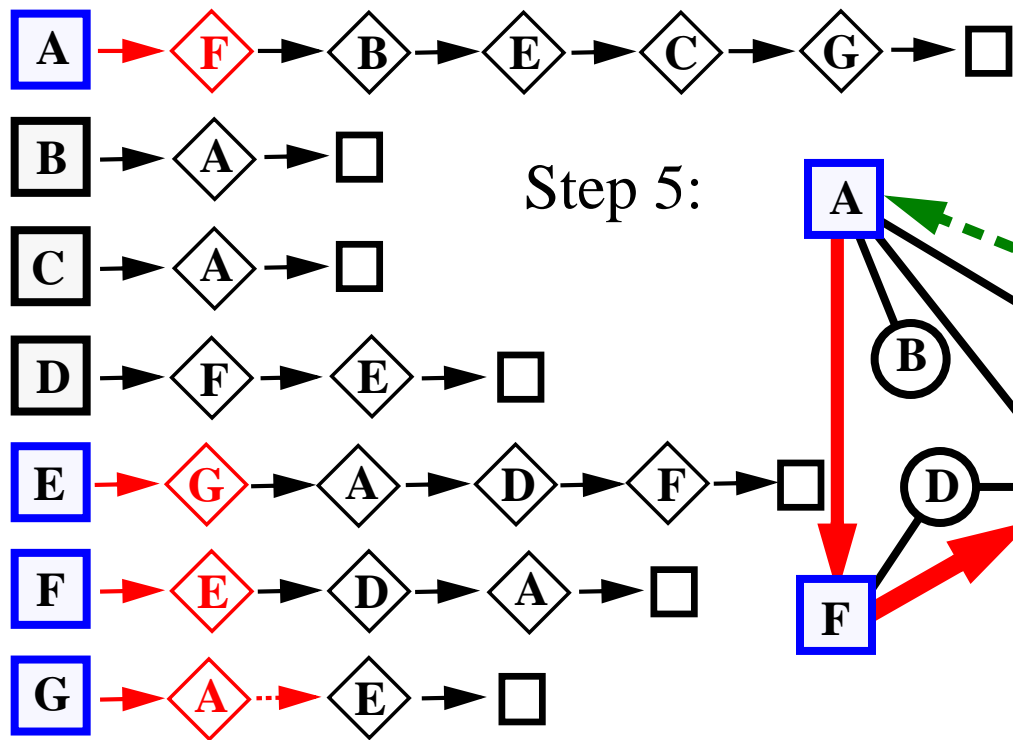


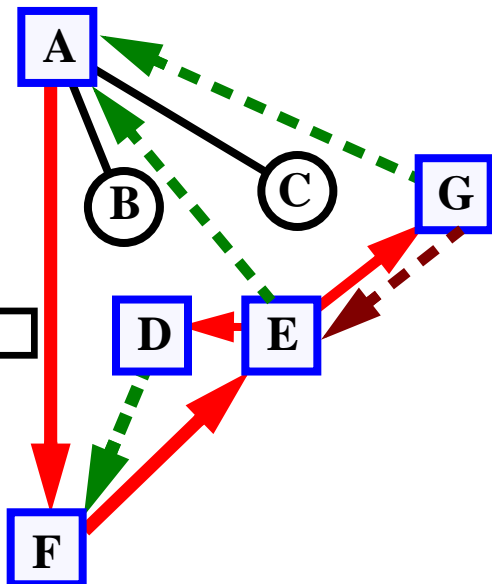
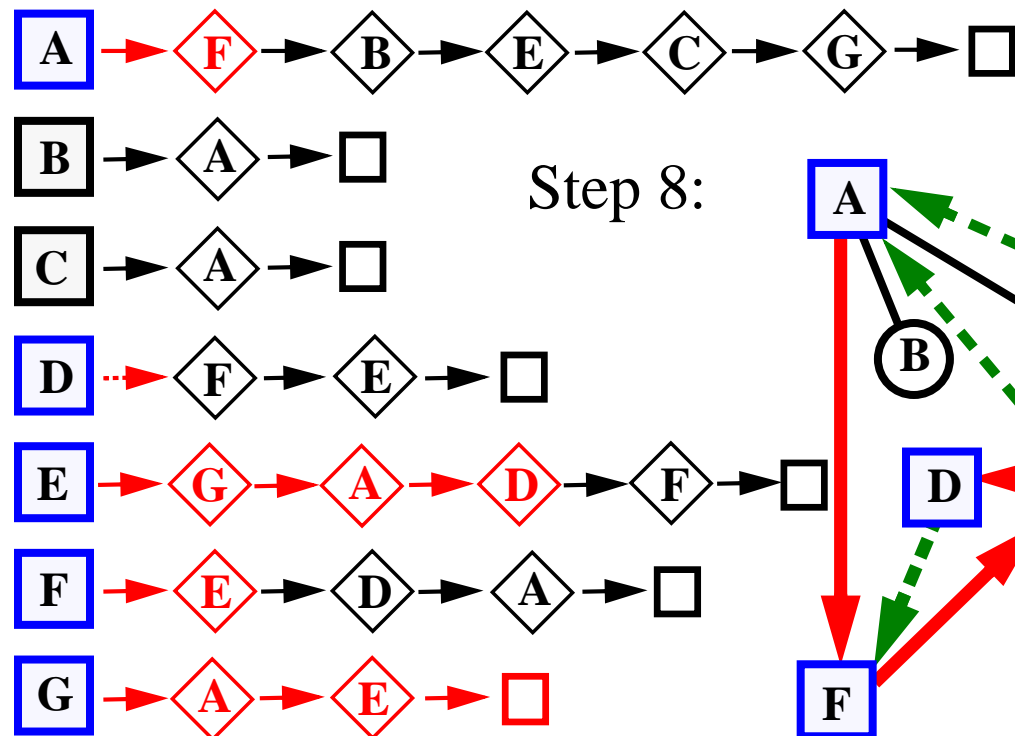
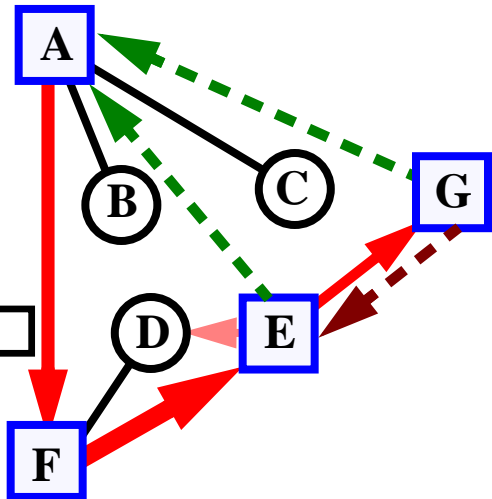
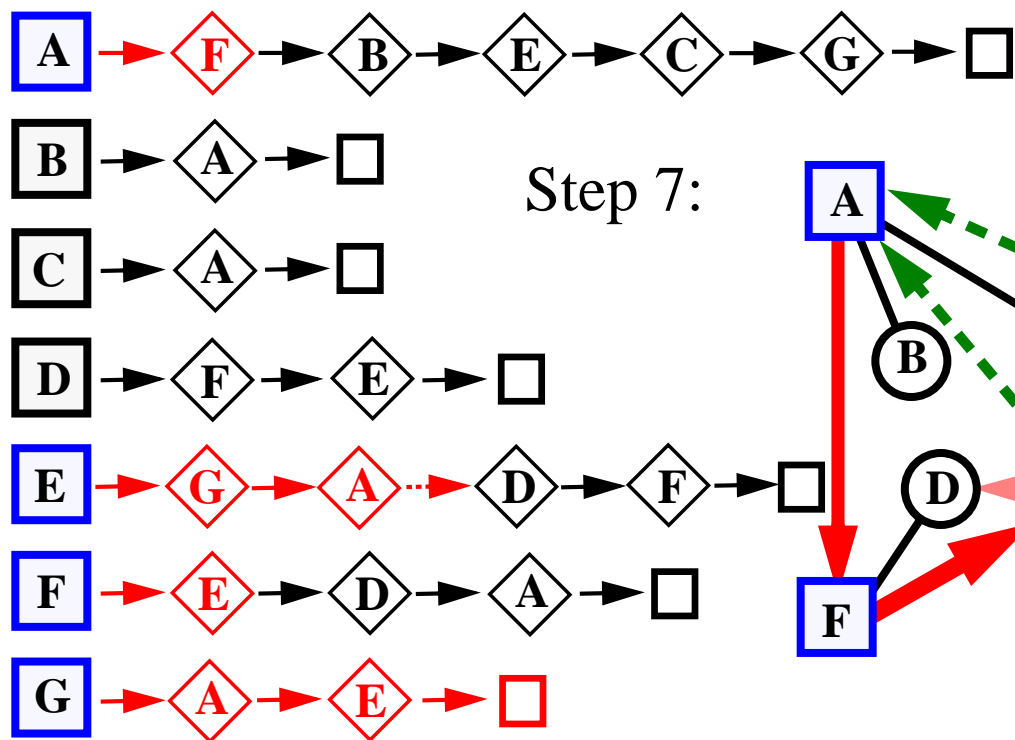
Step 3:

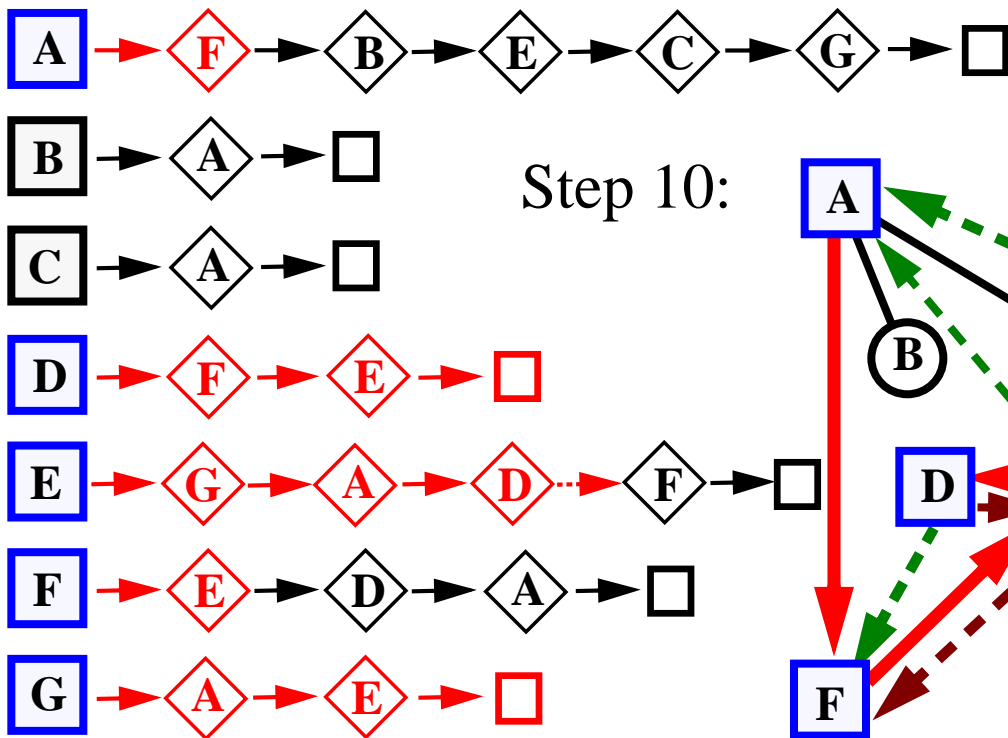
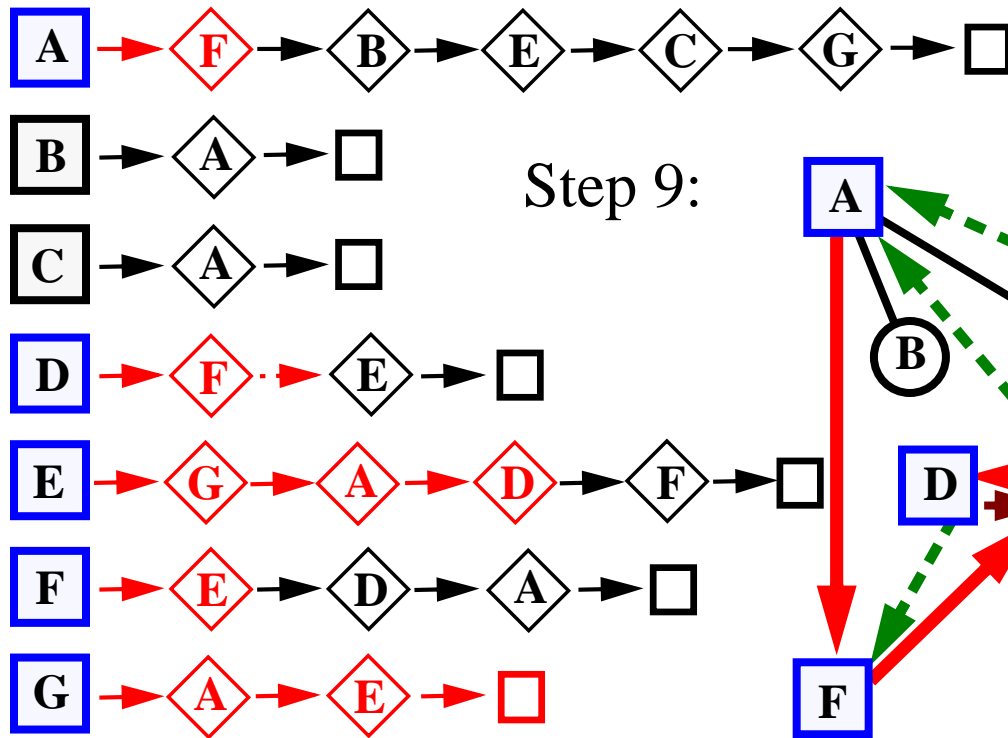


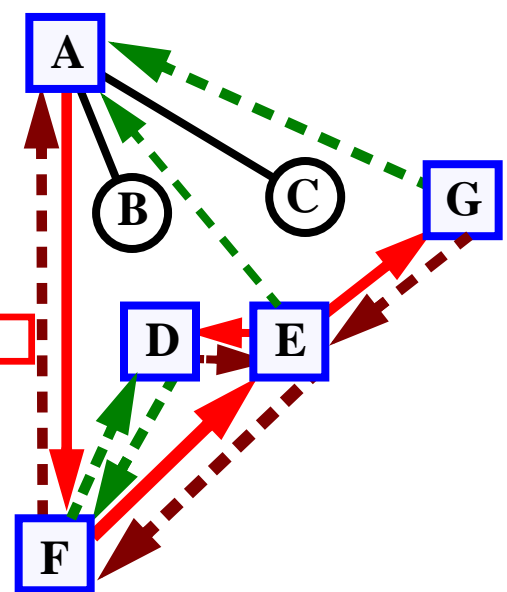
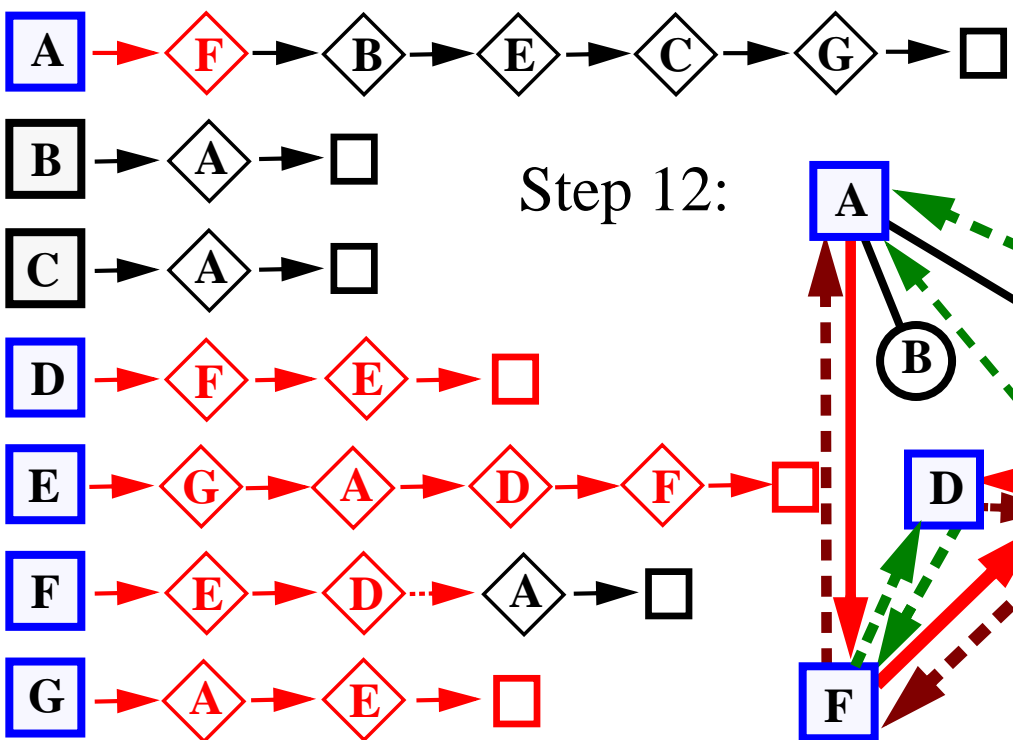
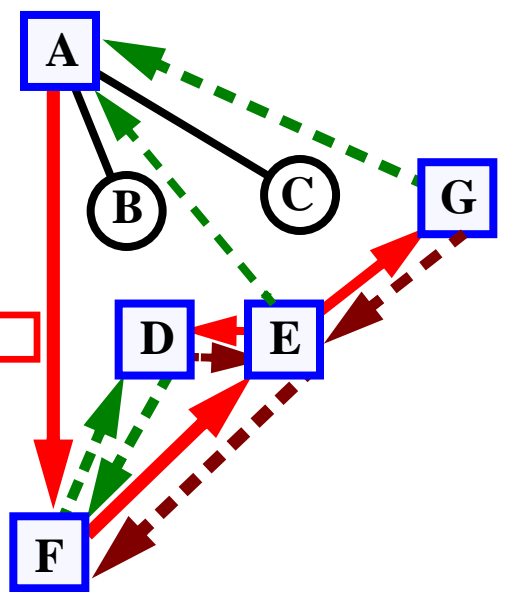
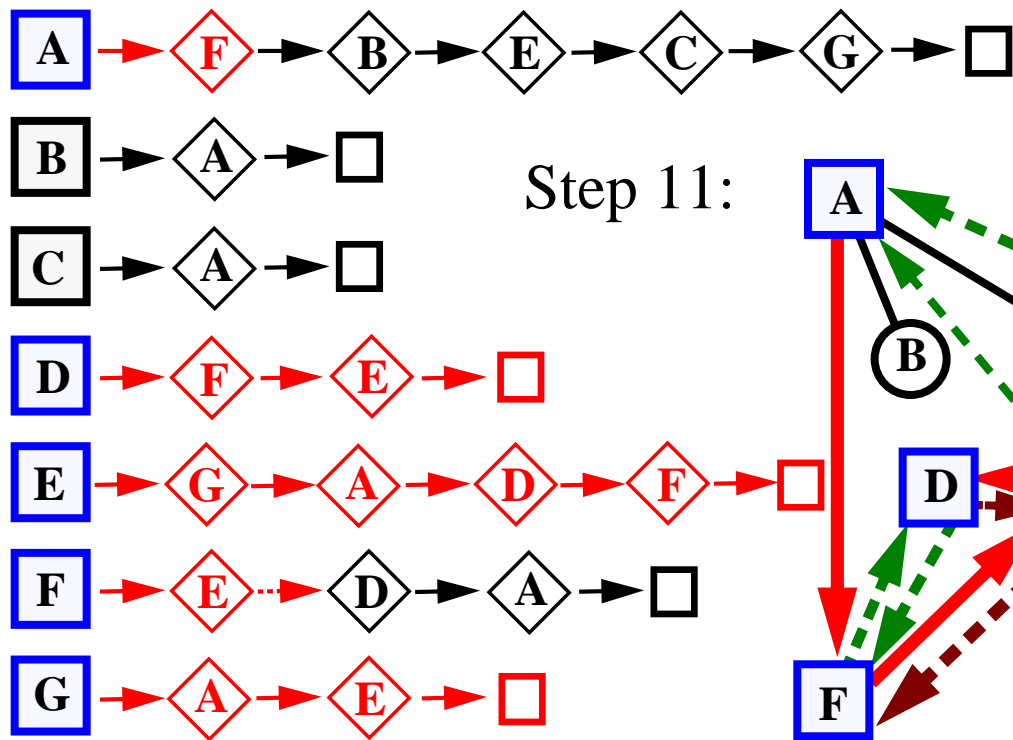
Step 4:

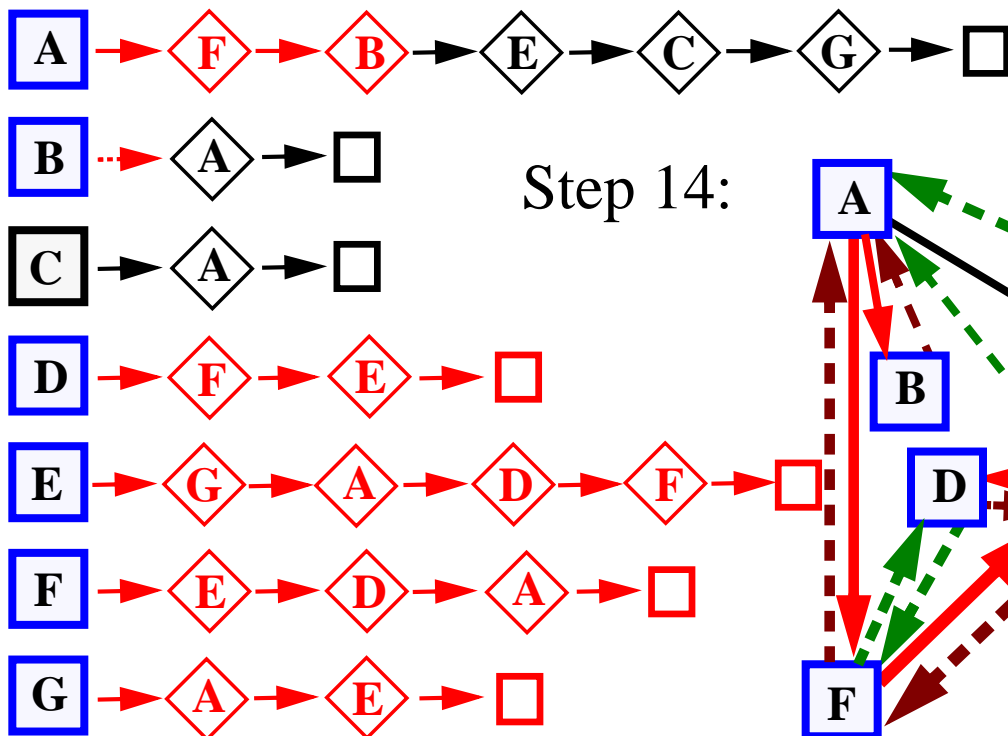
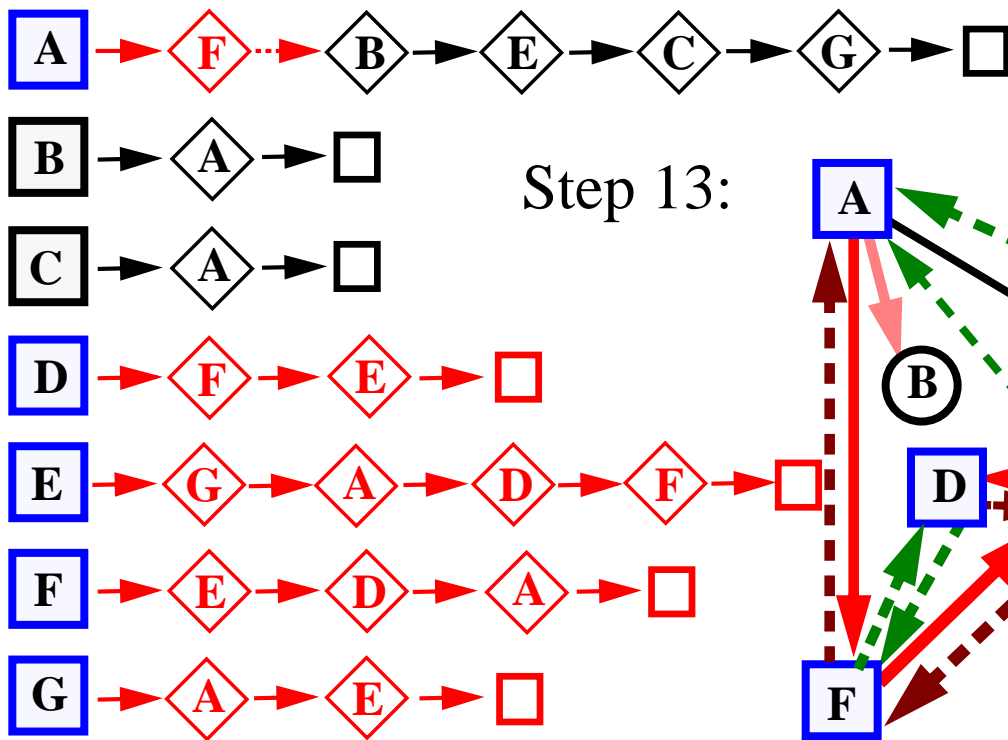


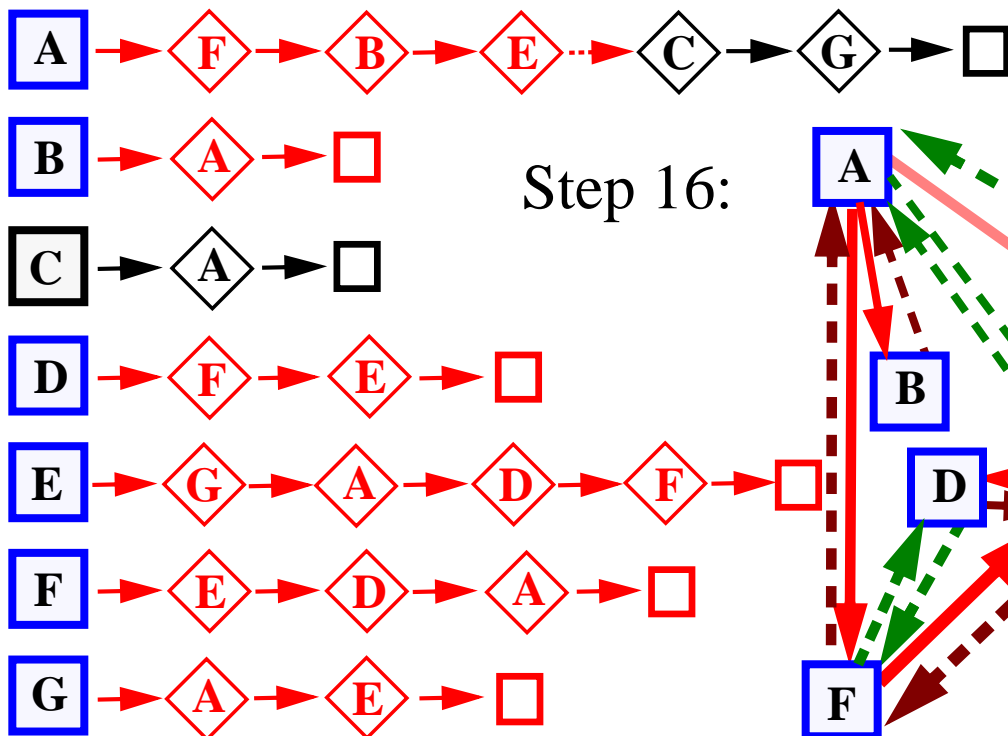
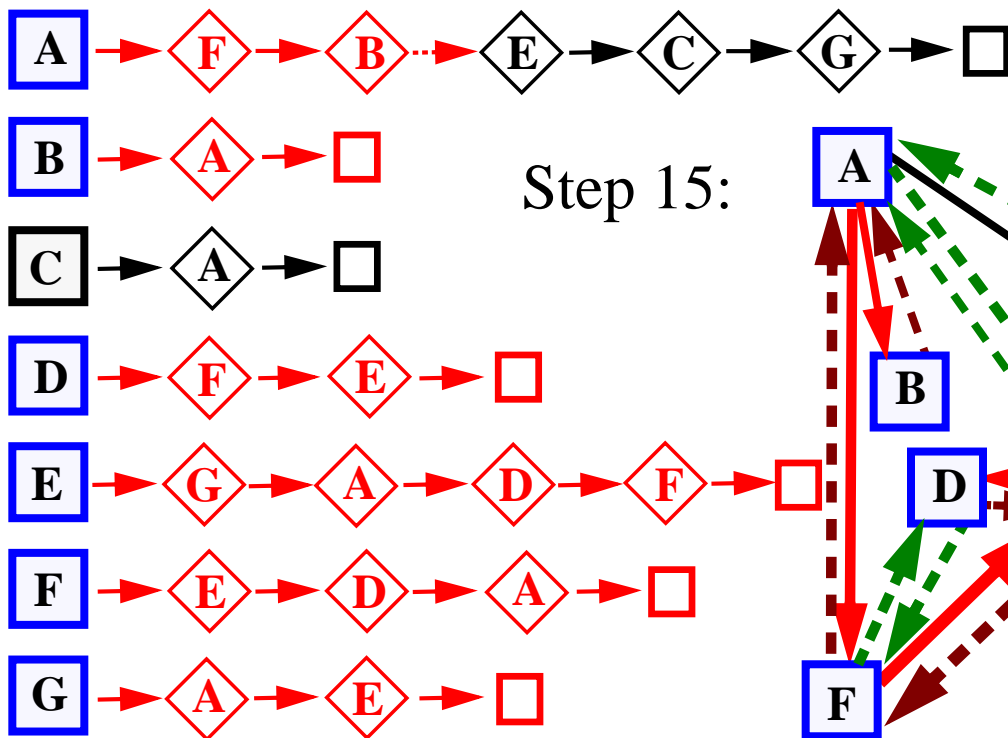


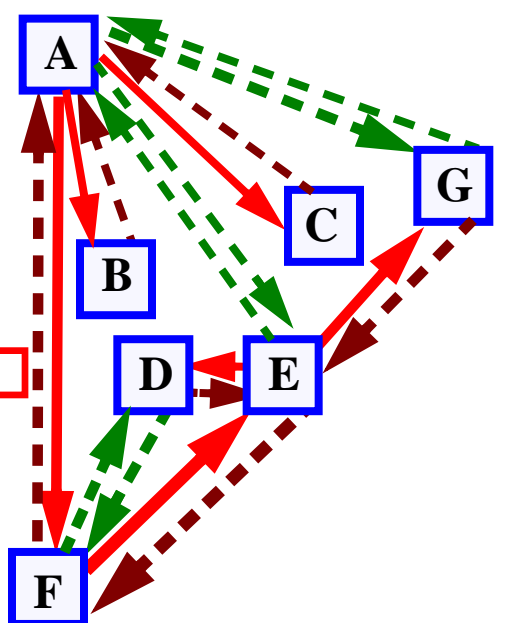
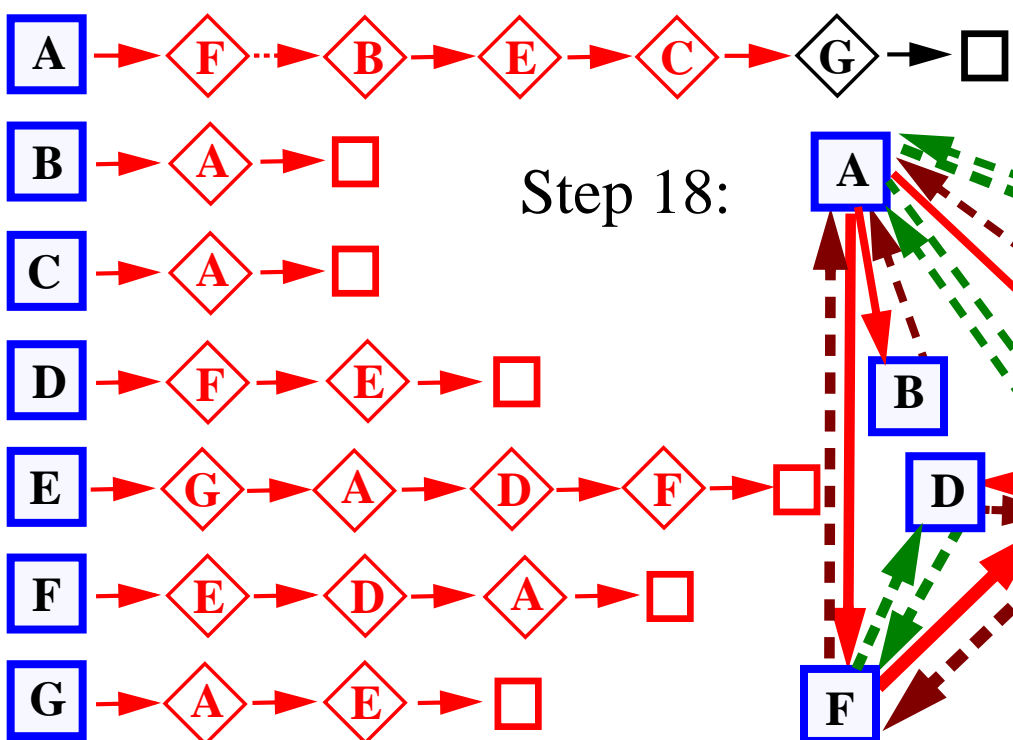
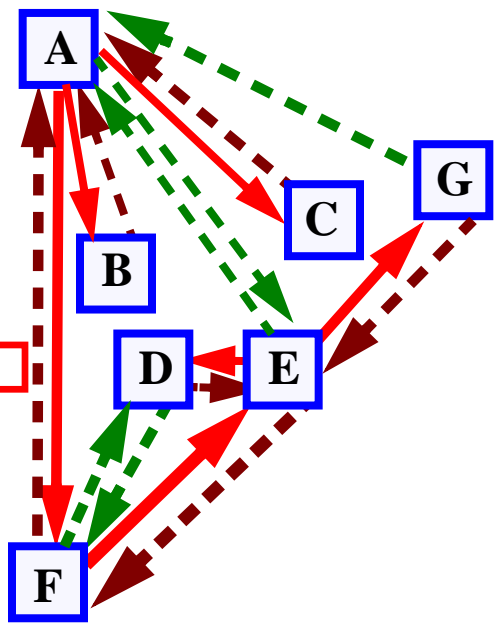
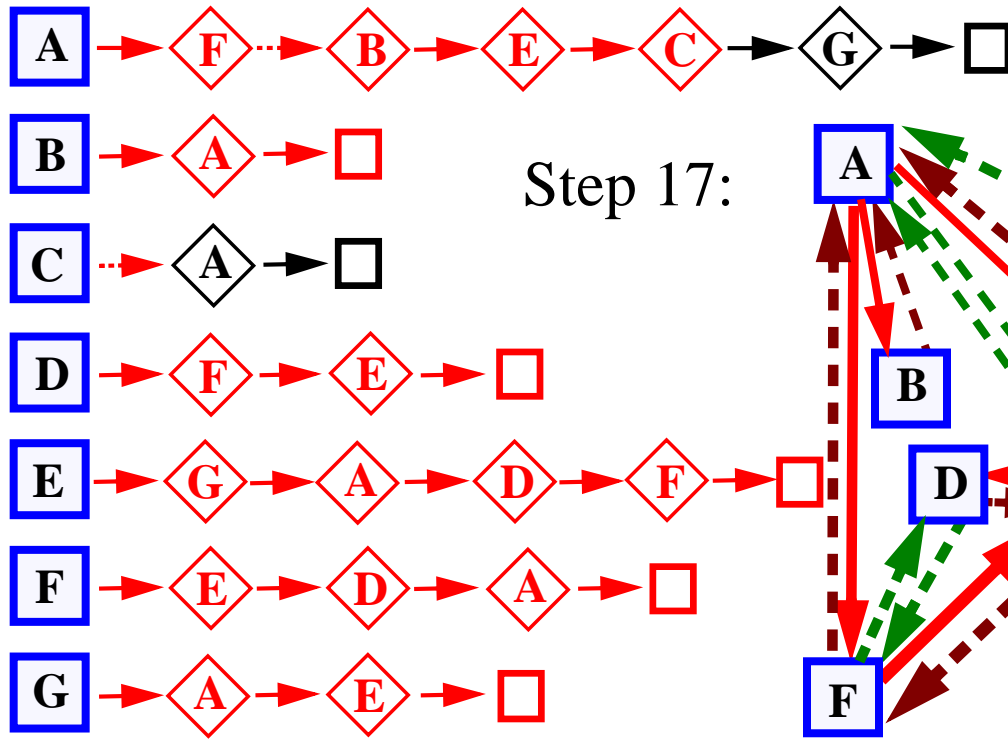


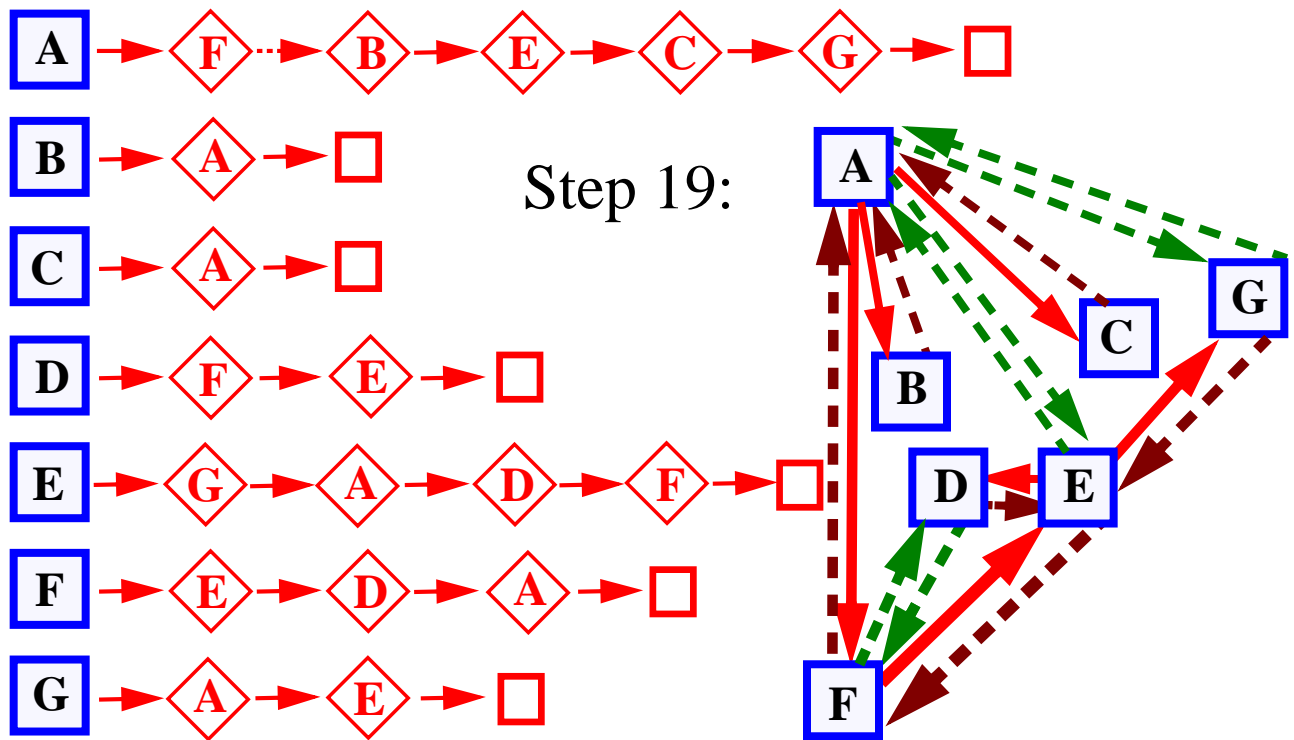












And we're done!

DFS Properties

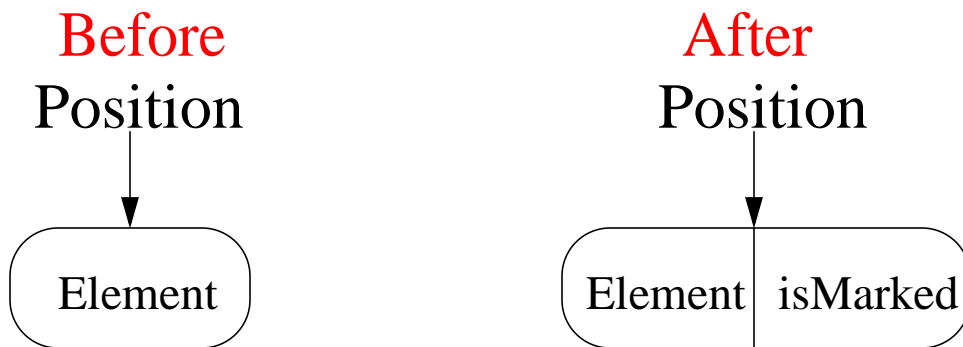
- Proposition 9.12 : Let G be an undirected graph on which a **DFS** traversal starting at a vertex s has been performed. Then:
 - 1) The traversal visits all vertices in the connected component of s
 - 2) The discovery edges form a spanning tree of the connected component of s
- Justification of 1):
 - Let's use a contradiction argument: suppose there is at least one vertex v not visited and let w be the first unvisited vertex on some path from s to v .
 - Because w was the first unvisited vertex on the path, there is a neighbor u that has been visited.
 - But when we visited u we must have looked at edge (u, w) . Therefore w must have been visited.
 - and justification
- Justification of 2):
 - We only mark edges from when we go to unvisited vertices. So we never form a cycle of discovery edges, i.e. discovery edges form a tree.
 - This is a spanning tree because **DFS** visits each vertex in the connected component of s

Running Time Analysis

- Remember:
 - **DFS** is called on each vertex exactly once.
 - Every edge is examined exactly twice, once from each of its vertices
- For n_s vertices and m_s edges in the connected component of the vertex s , a **DFS** starting at s runs in $O(n_s + m_s)$ time if:
 - The graph is represented in a data structure, like the adjacency list, where vertex and edge methods take constant time
 - Marking a vertex as explored and testing to see if a vertex has been explored takes $O(\text{degree})$
 - By marking visited nodes, we can systematically consider the edges incident on the current vertex so we do not examine the same edge more than once.

Marking Vertices

- Let's look at ways to mark vertices in a way that satisfies the above condition.
- Extend vertex positions to store a variable for marking



- Use a hash table mechanism which satisfies the above condition in the probabilistic sense, because it supports the mark and test operations in $O(1)$ expected time

The Template Method Pattern

- the **template method** pattern provides a *generic computation mechanism* that can be specialized by redefining certain steps
- to apply this pattern, we design a class that
 - implements the *skeleton* of an algorithm
 - invokes auxiliary methods that can be redefined by its subclasses to perform useful computations
- **Benefits**
 - makes the correctness of the specialized computations rely on that of the skeleton algorithm
 - demonstrates the power of class inheritance
 - provides code reuse
 - encourages the development of generic code
- **Examples**
 - *generic traversal of a binary tree* (which includes preorder, inorder, and postorder) and its applications
 - *generic depth-first search of an undirected graph* and its applications

Generic Depth First Search

```
public abstract class DFS {
    protected Object dfsVisit(Vertex v) {
        protected InspectableGraph graph;
        protected Object visitResult;
        initResult();
        startVisit(v);
        mark(v);
        for (Enumeration inEdges = graph.incidentEdges(v);
            inEdges.hasMoreElements();) {
            Edge nextEdge = (Edge) inEdges.nextElement();
            if (!isMarked(nextEdge)) { // found an unexplored edge
                mark(nextEdge);
                Vertex w = graph.opposite(v, nextEdge);
                if (!isMarked(w)) { // discovery edge
                    mark(nextEdge);
                    traverseDiscovery(nextEdge, v);
                    if (!isDone())
                        visitResult = dfsVisit(w); }
                else // back edge
                    traverseBack(nextEdge, v);
            }
        }
        finishVisit(v);
        return result();
    }
}
```

Auxiliary Methods of the Generic DFS

```
public Object execute(InspectableGraph g, Vertex start,
                    Object info) {
    graph = g;
    return null;
}

protected void setResult() {}

protected void startVisit(Vertex v) {}

protected void traverseDiscovery(Edge e, Vertex from) {}

protected void traverseBack(Edge e, Vertex from) {}

protected boolean isDone() { return false; }

protected void finishVisit(Vertex v) {}

protected Object result() { return new Object(); }
```

Now let's look at 4 way to specialize the generic DFS!

- class **FindPath** specializes **DFS** to return a path from vertex **start** to vertex **target**.

```
public class FindPathDFS extends DFS {
    protected Sequence path;
    protected boolean done;
    protected Vertex target;
    public Object execute(InspectableGraph g, Vertex start,
                          Object info) {
        super.execute(g, start, info);
        path = new NodeSequence();
        done = false;
        target = (Vertex) info;
        dfsVisit(start);
        return path.elements();
    }
    protected void startVisit(Vertex v) {
        path.insertFirst(v);
        if (v == target) { done = true; }
    }
    protected void finishVisit(Vertex v) {
        if (!done) path.remove(path.first());
    }
    protected boolean isDone() { return done; }
```

Other Specializations of the Generic DFS

- **FindAllVertices** specializes **DFS** to return an enumeration of the vertices in the connected component containing the **start** vertex.

```
public class FindAllVerticesDFS extends DFS {
    protected Sequence vertices;
    public Object execute(InspectableGraph g, Vertex start,
                        Object info) {
        super.execute(g, start, info);
        vertices = new NodeSequence();
        dfsVisit(start);
        return vertices.elements();
    }

    public void startVisit(Vertex v) {
        vertices.insertLast(v);
    }
}
```

More Specializations of the Generic DFS

- **ConnectivityTest** uses a specialized **DFS** to test if a graph is connected.

```
public class ConnectivityTest {
    protected static DFS tester = new
    FindAllVerticesDFS();
    public static boolean isConnected(InspectableGraph g)
    {
        if (g.numVertices() == 0) return true; //empty is
                                                //connected
        Vertex start = (Vertex)g.vertices().nextElement();
        Enumeration compVerts =
            (Enumeration)tester.execute(g, start, null);
        // count how many elements are in the enumeration
        int count = 0;
        while (compVerts.hasMoreElements()) {
            compVerts.nextElement();
            count++;
        }
        if (count == g.numVertices()) return true;
        return false;
    }
}
```


Another Specialization of the Generic DFS

- **FindCycle** specializes **DFS** to determine if the connected component of the **start** vertex contains a **cycle**, and if so return it.

```
public class FindCycleDFS extends DFS {
    protected Sequence path;
    protected boolean done;
    protected Vertex cycleStart;
    public Object execute(InspectableGraph g, Vertex start,
                        Object info) {

        super.execute(g, start, info);
        path = new NodeSequence();
        done = false;
        dfsVisit(start);

        //copy the vertices up to cycleStart from the path to
        //the cycle sequence.
        Sequence theCycle = new NodeSequence();
        Enumeration pathVerts = path.elements();
```

```

while (pathVerts.hasMoreElements()) {
    Vertex v = (Vertex)pathVerts.nextElement();
    theCycle.insertFirst(v);
    if ( v == cycleStart) {
        break;
    }
}
return theCycle.elements();
}

protected void startVisit(Vertex v) {path.insertFirst(v);}
protected void finishVisit(Vertex v) {
    if (done) {path.remove(path.first());}
}

//When a back edge is found, the graph has a cycle
protected void traverseBack(Edge e, Vertex from) {
    Enumeration pathVerts = path.elements();
    cycleStart = graph.opposite(from, e);
    done = true;
}

protected boolean isDone() {return done;}
}

```

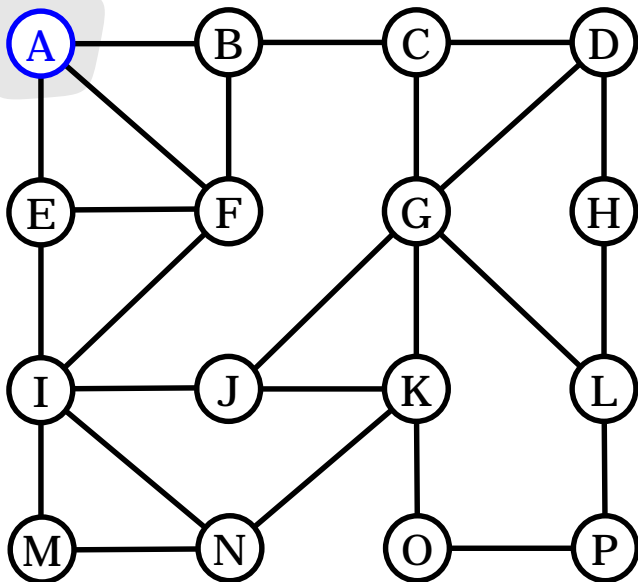
Breadth-First Search

- Like **DFS**, a **Breadth-First Search (BFS)** traverses a connected component of a graph, and in doing so defines a spanning tree with several useful properties
 - The starting vertex s has level 0, and, as in **DFS**, defines that point as an “anchor.”
 - In the first round, the string is unrolled the length of one edge, and all of the edges that are only one edge away from the anchor are visited.
 - These edges are placed into level 1
 - In the second round, all the new edges that can be reached by unrolling the string 2 edges are visited and placed in level 2.
 - This continues until every vertex has been assigned a level.
 - The label of any vertex v corresponds to the length of the shortest path from s to v .

BFS - A Graphical Representation

a)

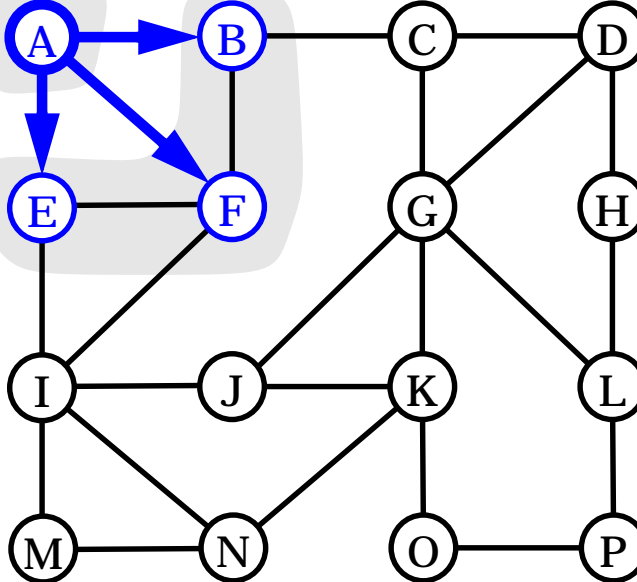
0



b)

0

1

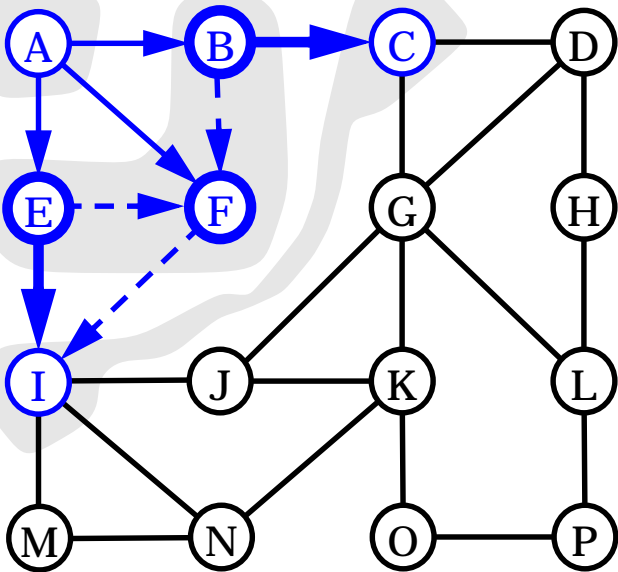


c)

0

1

2



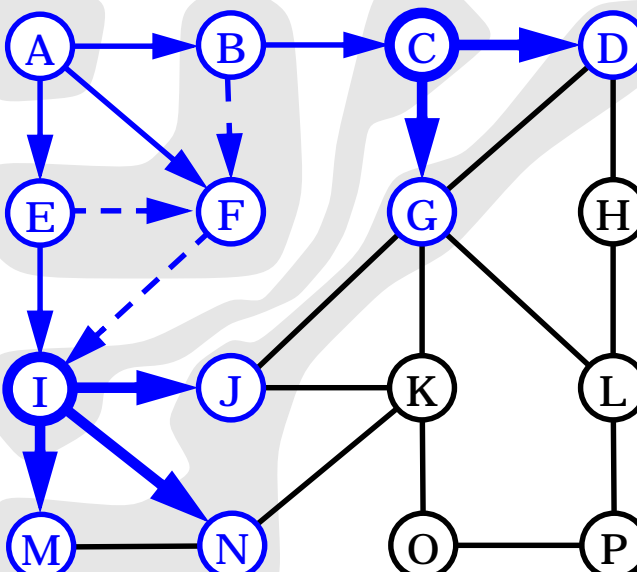
d)

0

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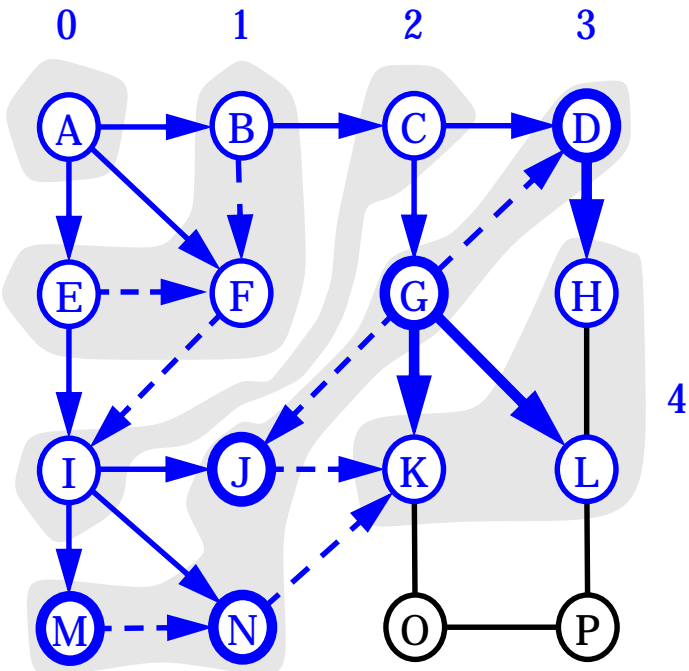
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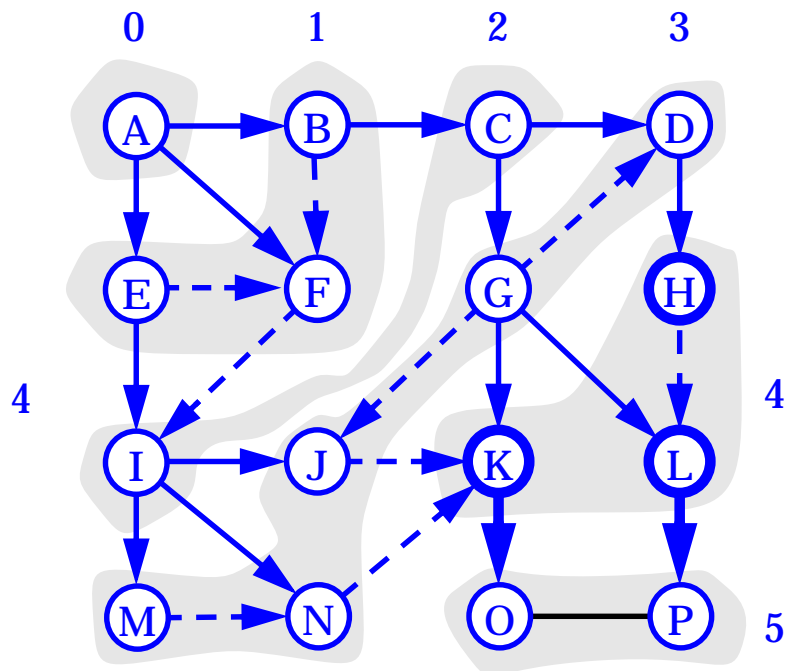


More BFS

e)



f)



BFS Pseudo-Code

Algorithm **BFS**(s):

Input: A vertex s in a graph

Output: A labeling of the edges as “discovery” edges and “cross edges”

initialize container L_0 to contain vertex s

$i \leftarrow 0$

while L_i is not empty do

 create container L_{i+1} to initially be empty

 for each vertex v in L_i do

 if edge e incident on v do

 let w be the other endpoint of e

 if vertex w is unexplored then

 label e as a discovery edge

 insert w into L_{i+1}

 else

 label e as a cross edge

$i \leftarrow i + 1$

Properties of BFS

- **Proposition:** Let G be an undirected graph on which a **BFS** traversal starting at vertex s has been performed. Then
 - The traversal visits all vertices in the connected component of s .
 - The discovery-edges form a spanning tree T , which we call the **BFS** tree, of the connected component of s
 - For each vertex v at level i , the path of the **BFS** tree T between s and v has i edges, and any other path of G between s and v has at least i edges.
 - If (u, v) is an edge that is not in the **BFS** tree, then the level numbers of u and v differ by at most one.
- **Proposition:** Let G be a graph with n vertices and m edges. A **BFS** traversal of G takes time $O(n + m)$. Also, there exist $O(n + m)$ time algorithms based on BFS for the following problems:
 - Testing whether G is connected.
 - Computing a spanning tree of G
 - Computing the connected components of G
 - Computing, for every vertex v of G , the minimum number of edges of any path between s and v .