Connectivity and Biconnectivity



- connected components
- cutvertices
- biconnected components



Connected Components

Connected Graph: any two vertices connected by a path





connected

not connected

Connected Component: maximal connected subgraph of a graph



Equivalence Relations

A *relation* on a set S is a set R of ordered pairs of elements of S defined by some property

Example:

- $\mathbf{S} = \{1, 2, 3, 4\}$
- $\mathbf{R} = \{(i,j) \in S \times S \text{ such that } i < j\}$ = $\{(1,2),(1,3),(1,4),(2,3),(2,4),\{3,4)\}$

An *equivalence relation* is a relation with the following properties:

- $(x,x) \in \mathbb{R}, \forall x \in \mathbb{S}$ (*reflexive*)
- $(x,y) \in \mathbb{R} \implies (y,x) \in \mathbb{R}$ (symmetric)
- $(x,y), (y,z) \in \mathbb{R} \implies (x,z) \in \mathbb{R}$ (transitive)

The relation C on the set of vertices of a graph:

• $(u,v) \in \mathbb{C} \iff u$ and v are in the same connected component

is an equivalence relation.



DFS on a Disconnected Graph

• DFS(*v*) visits all the vertices and edges in the connected component of *v*





Cutvertices

Cutvertex (separation vertex): its removal disconnects the graph

If the Chicago airport is closed, then there is no way to get from Providence to cities on the west coast.

Similarly for **Denver**.





Biconnectivity

Biconnected graph: has no cutvertices



New flights: LGA-ATL and DFW-LAX make the graph biconnected.



Properties of Biconnected Graphs



- There are *two disjoint paths* between any two vertices.
- There is a *cycle* through any two vertices.

By convention, two nodes connected by an edge form a biconnected graph, but this does not verify the above properties.





Biconnected Components

• Biconnected component (block): maximal biconnected subgraph



• Biconnected components are edge-disjoint but share cutvertices.



Characterization of the Biconnected Components

- *Equivalence relation* R on the *edges* of G: (e', e") ∈ R if there is a cycle containing both e' and e"
- Proof of the *transitive property*



- We partition the edges of G into *equivalence classes* with respect to R.
- Each equivalence class corresponds to
 - a biconnected components of G
 - a connected components of a graph H whose vertices are the *edges* of G and whose edges are the *pairs* in relation R.



DFS and Biconnected Components

- Graph H has $O(m^2)$ edges in the worst case.
- Instead of computing the entire graph H, we use a smaller *proxy* graph K.
- Start with an empty graph K whose vertices are the edges of G.
- Given a DFS on G, consider the (m n + 1) cycles of G induced by the back edges.
- For each such cycle $C = (e_0, e_1, \dots, e_p)$ add edges $(e_0, e_1) \dots (e_0, e_p)$ to K.



• The connected components of K are the same as those of H!



A Linear Time Algorithm

• The size of K is O(*mn*) in the worst case.



- We can further reduce the size of the proxy graph to O(*m*)
- Process the back edges according to a *preorder visit* of their destination vertex in the DFS tree
- Mark the discovery edges forming the cycles
- Stop adding edges to the proxy graph after the first marked edge is encountered.
- The resulting proxy graph is a forest!
- This algorithm runs in O(n+m) time.



Example

• Back edges labeled according to the preorder visit of their destination vertex in the DFS tree



• Processing e_1

• Processing e_2







Example (contd.)

• DFS tree

• final proxy graph (a tree since the graph is biconnected)



Why Preorder?

- The order in which the back edges are processed is essential for the correctness of the algorithm
- Using a different order ...



CS 16: Connectivity



