

On Bounds for Network Codes

Eimear Byrne

Claude Shannon Institute and
School of Mathematical Sciences
University College Dublin
Ireland

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Network Coding for Error Correction

- Yang, Yeung, Cai, Zhang introduced error correction in coherent networks, where the network topology is known to the receiver.
 - ideas from classical coding theory
- Kötter, Kschischang, Silva describe error correction where the network topology is not known to the receiver.
 - subspace codes
 - rank metric codes
 - matrix channels

The Alphabet

R is a finite ring and \mathcal{A} is a bimodule over R such that

$$\mathcal{A}_R \cong \text{Hom}(R, \mathbb{C}^\times)_R =: \hat{R}_R \text{ and } {}_R\mathcal{A} \cong {}_R\text{Hom}(R, \mathbb{C}^\times) =: {}_R\hat{R}$$

- $R = \mathcal{A} = \mathbb{F}_q$
- $R = \mathcal{A} = \mathbb{F}_q^{n \times n}$
- $R = \mathcal{A} = GR(p^n, m)$
- $R = \mathcal{A} =$ a Frobenius ring
- R any finite ring $\mathcal{A} = \hat{R}$

The Network

- The network is a directed acyclic graph \mathcal{N} with n unit edge capacities, a source node s and several sinks $t \in \mathcal{T}$
- The source transmits messages from a set of size M

$$\mathcal{M} = \{(x_0, 0) : x_0 \in \mathcal{M}_0 \subset \mathcal{A}^m, 0 \in \mathcal{A}^{n-m}\}.$$

- The **transfer function** is an R -automorphism

$$\mathcal{F} : \mathcal{A}^n \longrightarrow \mathcal{A}^n : z \mapsto (f_1(z), \dots, f_n(z)).$$

- If x is transmitted from s and edges of the network are corrupted by an error $e \in \mathcal{A}^n$ then the network transmission is

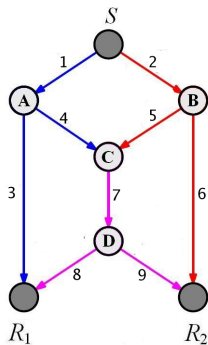
$$y = \mathcal{F}(x + e).$$

Example - The Butterfly Network

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$$T = \begin{bmatrix} 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$



Transfer Function for the Butterfly Network

The transfer function for the Butterfly Network is given by the matrix

$$F = I + T + T^2 + T^3 = (I - T)^{-1}$$
$$F = \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

The Transfer Function for each Receiver

- The transfer function for sink t is the R -epimorphism

$$\mathcal{F}_t : \mathcal{A}^n \longrightarrow \mathcal{A}^{n_t} : z \mapsto (f_i(z))_{i \in E_t},$$

where E_t is the set of n_t edges incident with t .

- Sink t receives

$$y = \mathcal{F}_t(x + e) \in \mathcal{A}^{n_t}.$$

- The network code for t is the set

$$\mathcal{C}_t := \{\mathcal{F}_t(x) \in \mathcal{A}^{n_t} : x \in \mathcal{M}\} \subset \mathcal{A}^{n_t}.$$

- Messages $z, z' \in \mathcal{A}^n$ are identified if

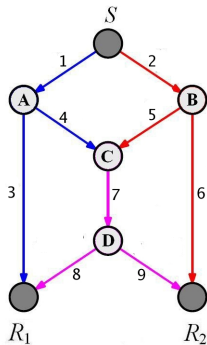
$$z - z' \in \ker \mathcal{F}_t =: K_t.$$

The Transfer Function for each Receiver

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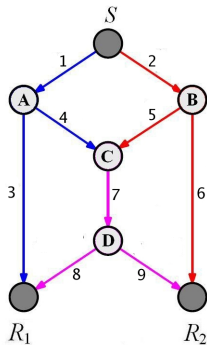


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The Transfer Function for each Receiver

If the message $x = [x_1, x_1, 0, 0, 0, 0, 0, 0, 0]$ is transmitted without error then receivers 1 and 2 get

$$xF_1 = x \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 0 \\ 0 & 1 \\ 0 & 1 \\ 0 & 0 \end{bmatrix} = [x_1, x_1 + x_2], \quad xF_2 = x \begin{bmatrix} 0 & 1 \\ 1 & 1 \\ 0 & 0 \\ 0 & 1 \\ 0 & 1 \\ 1 & 0 \\ 0 & 1 \\ 0 & 0 \\ 0 & 1 \end{bmatrix} = [x_2, x_1 + x_2].$$

$$\mathcal{C}_1, \mathcal{C}_2 \subset GF(2)^2.$$

Relevant Errors

- If x is sent and the error $e \in K_t$ occurs then

$$\mathcal{F}_t(x + e) = \mathcal{F}_t(x) \in \mathcal{C}_t$$

is received, as if without error.

- The decoder is only interested in errors e such that

$$\mathcal{F}_t(e) \neq 0.$$

A Distance Function

Given a distance function d on \mathcal{A}^n , K_t induces one on \mathcal{A}^{n_t} by

$$\begin{aligned}d_t(u, v) &:= \min\{d(x, y) : (u, v) = (\mathcal{F}_t(x), \mathcal{F}_t(y))\}, \\ &= d(x + K_t, y + K_t),\end{aligned}$$

where $(u, v) = (\mathcal{F}_t(x), \mathcal{F}_t(y))$.

Example

For

$$x \in R^n, F_t \in R^{n \times n_t}, \mathcal{F}_t(x) = xF_t$$

the Hamming distance induces a weight, $w_t(u) = d_t(u, 0)$, which counts the minimum number of linearly independent rows of F_t required to obtain a representation of $u = \mathcal{F}_t(x)$.

Weights Induced by K_1 for the Butterfly Network

Recall that for the Butterfly Network we have

$$F_1 = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 & 1 & 0 & 1 & 1 & 0 \end{bmatrix}^t.$$

K_1 induces the following weights on $GF(2)^2$.

\mathbf{c}	00	01	10	11
$\mathbf{c}F_1^{-1}$	K_1	$010\dots 0 + K_1$	$0010\dots 0 + K_1$	$10\dots 0 + K_1$
$w(\mathbf{c})$	0	1	1	1

Error Correction

- Given the received word y_t , the decoder at node t decides that $c = \mathcal{F}_t(x)$ has been transmitted if

$$d_t(y, c) < d_t(y, c')$$

for all $c' \in \mathcal{C}_t$.

- The decoder at node t can correct r errors if

$$d_t(\mathcal{C}_t) \geq 2r + 1.$$

- That is, if $d_t(\mathcal{C}_t) \geq 2r + 1$ then \mathcal{C}_t can correct any error pattern e satisfying $w_t(\mathcal{F}_t(e)) \leq r$.

Parameters of a Network Code

Definition

Let \mathcal{N} be a network with a set of sink nodes \mathcal{T} . Let \mathcal{F} be a transfer function for \mathcal{N} .

A network code \mathcal{C} for the network \mathcal{N} is a collection

$$\mathcal{C} := \{\mathcal{C}_t : t \in \mathcal{T}\},$$

where $\mathcal{C}_t = \{\mathcal{F}_t(x) : x \in \mathcal{M}\}$ is an (n_t, M, d_t) code.

The Size of a Network Code

Definition

We denote by

$$A(n, \{(n_t, \ell_t, d_t) : t \in \mathcal{T}\})$$

the maximum size of any $(n, \{(n_t, \ell_t, M, d_t) : t \in \mathcal{T}\})$ network code. We denote by

$$A(n, n_t, \ell_t, d_t)$$

the maximum size of any (n_t, ℓ_t, M, d_t) network code for sink t .

- $\ell_t := |\text{supp } K_t|$
- $\text{supp } K_t := \{i \in \{1, \dots, n\} : z_i \neq 0 \text{ some } z = (z_i)_{i=1}^n \in K_t\}$

Some Known Upper Bounds

Theorem (Yang *et al*, 2011)

Let $R = \mathcal{A} = GF(q)$. Then

$$A(n, \{(n_t, \ell_t, d_t) : t \in \mathcal{T}\}) \leq$$

- $\min \left\{ \frac{q^{n_t}}{\sum_{i=1}^{n_t} \binom{n_t}{i} (q-1)^i} : t \in \mathcal{T} \right\}$ (*sphere-packing bound*)
- $\min \left\{ q^{n_t - d_t + 1} : t \in \mathcal{T} \right\}$ (*refined Singleton bound*)

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- $\min \{ q^{n_t - d_t + 1} : t \in \mathcal{T} \}$ (*refined Singleton bound*)
- Plotkin bound?
- Elias bound?

The Classical Plotkin and Elias Bounds

The classical Plotkin and Elias bounds find upper and lower bounds on the sum of the distances between codewords of an $(n, |C|, d)$ code for the homogeneous weight.

$$|C|(|C| - 1)d \leq \sum_{x,y \in C} d(x,y) = \sum_{i=1}^n \sum_{x,y \in C} d(x_i, y_i)$$

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$$\begin{aligned} |C|(|C| - 1)d &\leq \sum_{x, y \in C} d(x, y) = \sum_{i=1}^n \sum_{x, y \in C} d(x_i, y_i) \\ &\leq \begin{cases} |C|^2 n \gamma & \text{Plotkin} \\ |C|^2 (2r - \frac{r^2}{\gamma n}) & \text{Elias} \end{cases} \\ &\quad r^2 - 2\gamma nr + \gamma nd > 0. \end{aligned}$$

“On Bounds for Codes Over Frobenius Rings Under Homogeneous Weights”, Greferath & O’Sullivan, Discrete Mathematics, 2004.

Pulling Back to the Network Code

These arguments work because the homogeneous weight of a word can be expressed as the sum of the weights of its components.

This is not true of the distance function for the network.

For example, the Butterfly Network matrix F_1 and the Hamming distance gives the induced weight:

\mathbf{c}	00	01	10	11
$w(\mathbf{c})$	0	1	1	1

The Homogeneous Weight

Definition

A weight function w on a left R -module \mathcal{A} is called homogeneous if

H1 If $Rx = Ry$ then $w(x) = w(y)$ for all $x, y \in \mathcal{A}$.

H2 There exists a real number γ such that

$$\sum_{y \in Rx} w(y) = \gamma |Rx| \quad \forall 0 \neq x \in \mathcal{A}.$$

This weight always exists on \mathcal{A} and is unique of to choice of γ .

Examples

- If $R = \mathcal{A} = GF(q)$, the Hamming weight is homogeneous with average weight $\gamma = \frac{q-1}{q}$.

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- If $R = \mathcal{A} = \mathbb{Z}_4$, the Hamming weight is not homogeneous, but the Lee weight is with average weight $\gamma = 1$.

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- If $R = \mathcal{A} = \mathbb{Z}_4$, the Hamming weight is not homogeneous, but the Lee weight is with average weight $\gamma = 1$.
- Let $R = \mathcal{A} = GF(q)^{2 \times 2}$. Then the weight

$$w(x) = \begin{cases} \frac{q^2-q-1}{q-1} & \text{if } \text{rank}(x) = 2, \\ q & \text{if } \text{rank}(x) = 1, \\ 0 & \text{if } x = 0, \end{cases}$$

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- $R = GF(q)$, $\mathcal{A} = GF(q)^{2 \times 2}$ the Hamming weight is homogeneous for $\gamma = \frac{q-1}{q}$.

A Plotkin Bound

Theorem

Let $d = \min\{d_t : t \in \mathcal{T}\} > \gamma n$ and let $\ell = \min\{\ell_t : t \in \mathcal{T}\}$.
Then

$$\begin{aligned} A(n, \{(n_t, \ell_t, d_t) : t \in \mathcal{T}\}) &\leq \min \left\{ \frac{d_t - \gamma \ell_t}{d_t - \gamma n} : t \in \mathcal{T} \right\} \\ &\leq \frac{d - \gamma \ell}{d - \gamma n}, \end{aligned}$$

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As $\ell \rightarrow 0$ this gives the classical Plotkin bound.

An Elias Bound

Theorem

Let $d_t \leq \gamma n$ and let

$$\gamma l_t \leq r \leq \gamma n - \sqrt{\gamma(\gamma n - d_t)(n - \gamma l_t)}.$$

Then $A(n, n_t, l_t, d_t) \leq$

$$\frac{\gamma(d_t - \gamma l_t)(n - l_t)|\mathcal{A}|^{n-l_t}}{[(r - \gamma n)^2 - \gamma(\gamma n - d_t)(n - \gamma l_t)]|B^{n-l_t}(r - \gamma l_t)|},$$

$B^{n-l_t}(r - \gamma l_t)$ is the sphere of radius $r - \gamma l_t$ about $0 \in \mathcal{A}^{n-l_t}$.

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As $l \rightarrow 0$ this gives the classical Elias bound.

The Homogeneity Property

A key property of the homogeneous weight that gives these results is the following fact.

Lemma

Let ${}_R\mathcal{A}_R$ be a Frobenius bimodule with homogenous weight function $w : \mathcal{A} \rightarrow \mathbb{R}$. Let C be an R -submodule of \mathcal{A}^n and let $x \in \mathcal{A}^n$. Then

$$\frac{1}{|C|} \sum_{c \in C} w(x + c) = \gamma |\text{supp } C| + w(\pi_{\text{supp } C}(x)).$$

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Corollary

$$w(x + C) \leq \gamma |\text{supp } C| + w(\pi_{\text{supp } C}(x)).$$

Asymptotic Bounds

Definition

$$\alpha(\{(\nu_t, \lambda_t, \delta_t) : t \in \mathcal{T}\}) := \limsup_{n \rightarrow \infty} \frac{1}{n} \log_{|\mathcal{A}|} (A(n, \{(\nu_t n, \lambda_t n, \delta_t n) : t \in \mathcal{T}\})).$$

We seek an upper bound on this quantity.

Asymptotic Bounds

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Definition

$$\alpha_t(\nu, \lambda, \delta) := \limsup_{n \rightarrow \infty} \frac{1}{n} \log_{|\mathcal{A}|} A(n, \nu n, \lambda n, \delta n).$$

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Asymptotic Bounds

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Theorem (Plotkin)

$$\alpha_t(\nu, \lambda, \delta) \leq \begin{cases} 0 & \text{if } \delta > \gamma \\ 1 - \frac{\delta}{\gamma} & \text{if } \delta \leq \gamma \end{cases}$$

Asymptotic Bounds

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Theorem (Singleton)

Let $0 < \delta < \nu < 1$. Then

$$\alpha_t(\nu, \delta, \lambda) \leq \nu - \delta.$$

Asymptotic Bounds

Theorem (Elias)

Let $\rho > 0$ and let $\nu, \lambda, \delta \in (0, 1)$ satisfy $\delta \leq \gamma$ and

$$\gamma\lambda \leq \rho \leq \gamma - \sqrt{\gamma(\gamma - \delta)(1 - \lambda)}.$$

Then

$$\alpha_t(\nu, \delta, \lambda) \leq 1 - \lambda - H\left(\gamma - \sqrt{\frac{\gamma(\gamma - \delta)(1 - \gamma\lambda)}{1 - \lambda}}\right).$$

where

$$H(\delta) := \limsup_{N \rightarrow \infty} N^{-1} \log_{|\mathcal{A}|} |B^N(\delta N)|$$

Asymptotic Bounds

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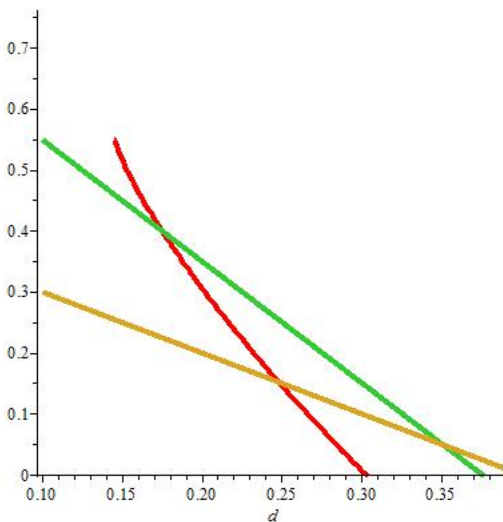
As $\lambda \rightarrow 0$, this quantity $\rightarrow 1 - H(\rho)$.

Bound Comparisons

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$$\nu = 0.4, \sigma = 0.75, \lambda = 0.45$$

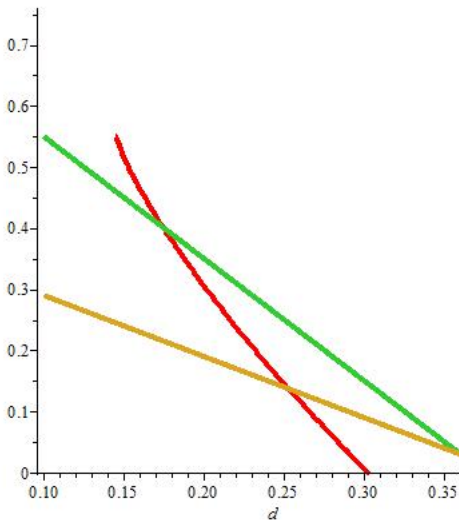


Bound Comparisons

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$$\nu = 0.39, \sigma = 0.75, \lambda = 0.45$$

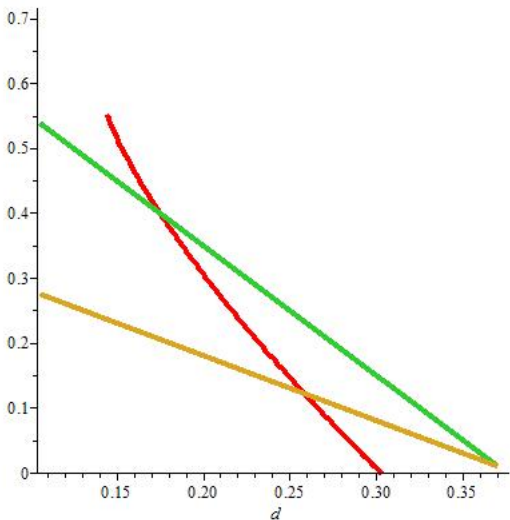


Bound Comparisons

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$$\nu = 0.38, \sigma = 0.75, \lambda = 0.45$$

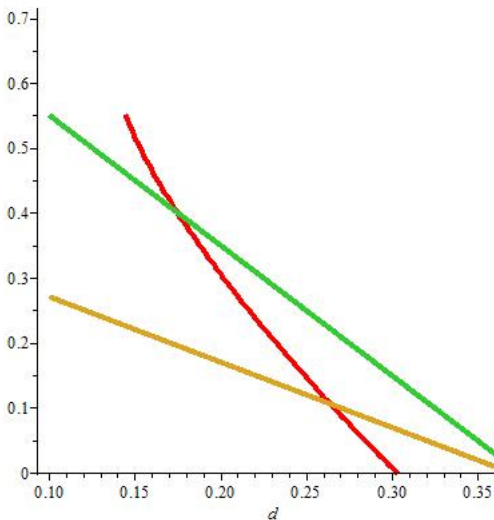


Bound Comparisons

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$$\nu = 0.37, \sigma = 0.75, \lambda = 0.45$$

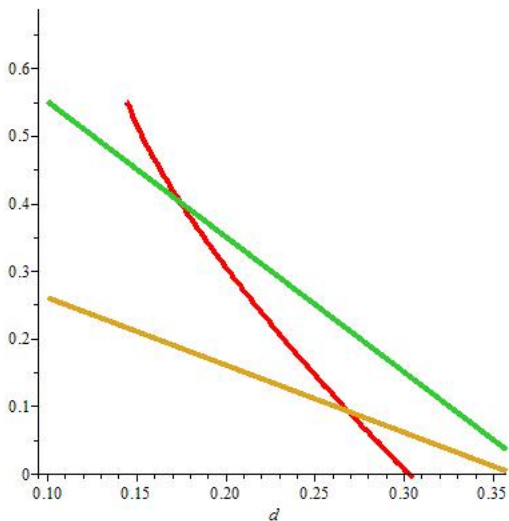


Bound Comparisons

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$$\nu = 0.36, \sigma = 0.75, \lambda = 0.45$$

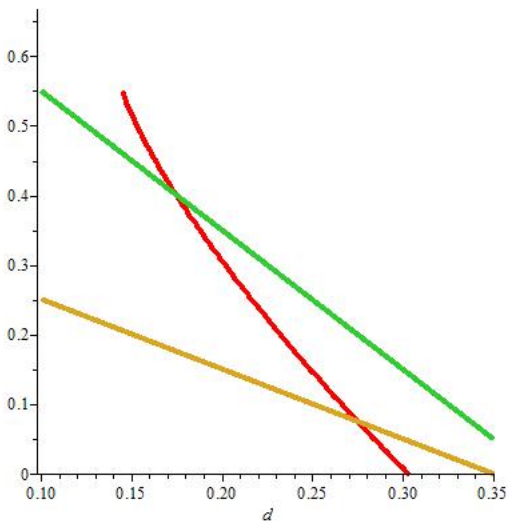


Bound Comparisons

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$$\nu = 0.35, \sigma = 0.75, \lambda = 0.45$$

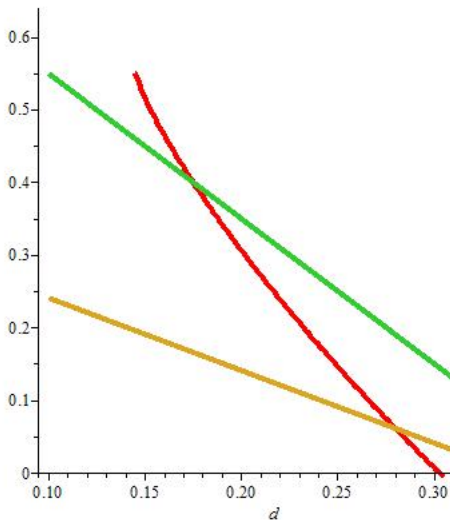


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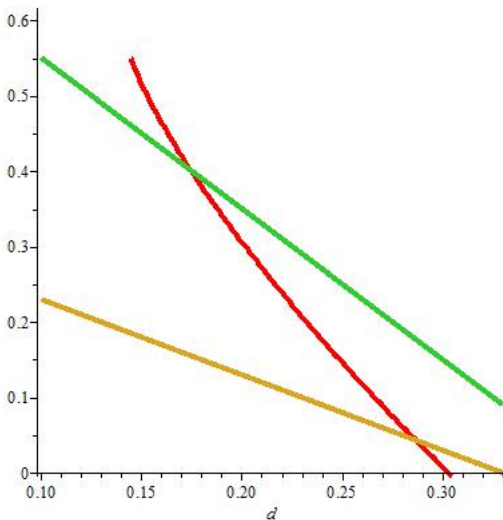


Bound Comparisons

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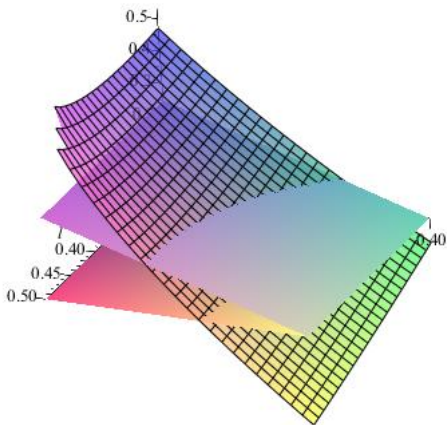


Elias and Singleton

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Elias and Singleton Bounds



Wakey, wakey..

Thanks!

References

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