

Optimization Methods for Pipeline Transportation of Natural Gas

– DISSERTATION –

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 - Three solution approaches
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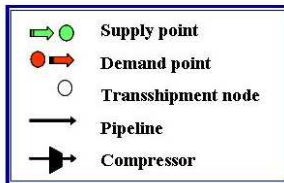
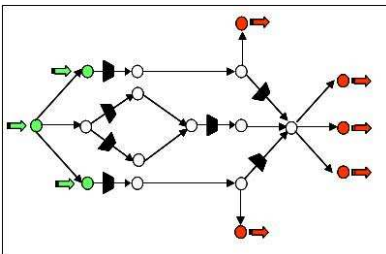
Project I: Operability on compressor stations

PROJECT I

Notation

The gas transmission network, variables and parameters

$G = (V, A) \Rightarrow$ A gas transmission network



DECISION VARIABLES:

x_{ij} : Mass flow rate in arc (i, j)

p_i : Pressure at node i

PARAMETERS:

P_i^L, P_i^U : Pressure limits at node $i \in V$;

B_i : Net mass flow rate at node $i \in V$.

(2) The NDP algorithm (Carter, 1998)

Basic principles of the NDP of Carter

- 1st : **Discretize** $[P_i^L, P_i^U], \forall i \in V$
Assume τ discretization points
 (p_i^1, \dots, p_i^τ) of pressure at node i ,
s.t. $P_i^L \leq p_i^1 < \dots < p_i^\tau \leq P_i^U$
- For instance, $[600, 800]$, $\tau = 20$.
We would consider only pressures at ten point increments: 600, 610, 620, \dots , 800.

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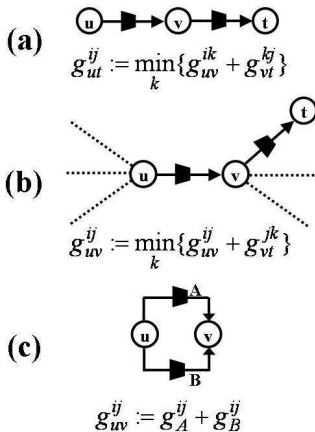
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point increments: 600, 610, 620, \dots , 800.

Then NDP consists of

- a sequence of reductions of G' until the resulting graph is a single node.
- 3 types are considered:
a) Serial, b) dangling and c) parallel.



Project I: Solving the FCMP

The 1st solution approach suggested for solving FCMP

⇒ **A Tabu Search scheme and non-sequential DP**

TS heuristic (Glover and Laguna, 1997) & NDP approach (Carter, 1998)

The 1st solution approach (suggested during my master)

Input: $G = (V, A)$

- STEP 0: Obtain a **reduced network** G' of G
- STEP 1: Find a feasible flow x in G'
- STEP 2: Apply **NDP to G' to optimize pressure p**
- STEP 3: Apply a TS heuristic to optimize (x, p) on G'
- STEP 4: Extend the best solution found to G

Output: Feasible flows and optimal pressures for G

Project I: *Solving the FCMP*

Conclusions on *the 1st solution approach*

Advantages:

- ✓ *Applicable to linear, tree-shaped & cyclic networks*
- ✓ *Easy to handle non-convexity*

Project I: Solving the FCMP

Conclusions on *the 1st solution approach*

Weakness:

- ▼ Limited to sparse networks

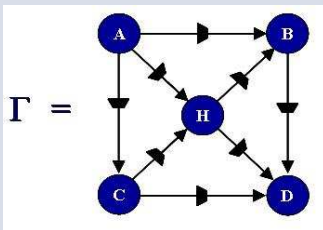
Project I: Solving the FCMP

Conclusions on the 1st solution approach

Weakness:

- ▼ Limited to sparse networks

An example of this limitation...



**When neither of the reductions (a)–(c)
can be carried out, NDP fails!**

Project I: Solving the FCMP

The 2nd solution approach (Contribution of the PhD thesis)

(To overcome this weakness...)

A 2nd solution approach

⇒ **A tree-decomposition based algorithm**

Frequency assignment problem via TD (Koster et al., 1999)

A tree-decomposition based algorithm

Devoted to optimize *pressure values*

TREEDDP ALGORITHM

Input: $G' = (V, A_c)$ = Compressor network

A feasible flow \mathbf{x} in G'

Phase 0: **Apply** NDP to $G' \rightarrow \Gamma$

Phase 1: **Find** a tree decomposition \mathbf{T} of Γ

Phase 2: **Apply** a DP to \mathbf{T}

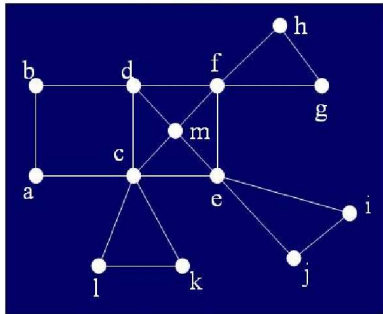
Output: Optimal pressure p^*

Phase 1: Tree Decomposition (TD)

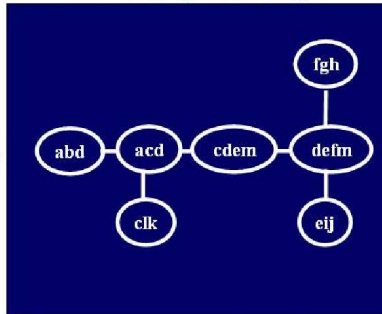
(Robertson and Seymour, 1986)

Basically, the main idea of a TD technique

Decompose the problem into a set of connected sub-problems, where two sub-problems are connected when they share a constraint.



Compressor network Γ



Tree decomposition T of Γ

To compute $\mathcal{F} \rightarrow$ TD technique based on *Maximum Cardinality Search* (MCS)

Phase 2: Dynamic Programming (DP)

(Bellman, 1953)

Now,

The principles of DP can be applied to T

Components of a global opt. sol. are themselves globally opt.

This completes the 2nd solution approach,
TreeDDP, proposed in this thesis

Project I: Numerical experiments

PERFORMANCE OF *TreeDDP* Algorithm

Observations for three different mesh sizes:

		$\tau = 50$	$\tau = 100$	$\tau = 1000$
CPU Time (sec):	AVG	0.0	3.2	1535 (0.4hr)
	MAX	2.6	34.4	3623 (1.0hr)*

- AVG-relative GAP from $\tau=1000$ to $\tau=50$: **42.17%**, $\tau=100$: **5.52%**

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Conclusion:

τ is crucial for the CPU-time

Numerical Experiments

TreeDDP Algorithm vs. other optimizers

TREEDDP ALGORITHM VS. BARON AND MINOS

Observations on 16 test instances:

- Instances solved by:
 - **Baron:** 8/16, **Minos:** 11/16, **TreeDDP:** 16/16
- AVG-RI of *TreeDDP* over:
 - Baron: 9.45%, Minos: 11.55%

Project I: Solving the FCMP

The 2nd solution approach

Conclusions on the 2nd solution approach

Advantages:

- ✓ *Applicable to a wide range of network topologies*
- ✓ *TreeDDP can be put inside an algorithm that considers flow variables in an outer loop.*

Project I: Solving the FCMP

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Weakness:

- ▼ *High dependency on the discretization, τ*

Project I: *Tackling the FCMP*

The 3rd solution approach (Contribution of the PhD thesis)

(To overcome the weakness presented by TreeDDP...)

The 3rd solution approach

⇒ **An adaptive discretization approach**

Based on some facts:

- ⊙ Assessing the number of discretization points, τ , is not a trivial task.
- ⊙ Large value of τ increases the possibility of finding a good solution.
- ⊙ The asymptotic increase in the running time of DP is proportional to τ^d .

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Project I: *Tackling the FCMP*

The 3rd solution approach

Main ideas behind the *adaptive discretization*

- Start with τ as small as possible
- Upgrade τ by a fixed factor until at least one feasible point is found by DP.
- For each solution in a selection of the feasible ones hence found:
 - Define a focus area for the next iteration
- Apply the same procedure to each focus area.

Project I: Solving the FCMP

The 3rd solution approach

Conclusions on the 3rd solution approach

Advantages:

- ✓ No assumption is made concerning the sparsity of the network
- ✓ Outperforms *the efficiency of **previous approaches***
(up to 16.3% of RI over a global optimizer)
- ✓ Effective in *solving large networks*
(< 60 CPU-seconds in 22 test cases)

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Weakness:

- ▼ As a heuristic method → *no guarantee of optimality*

Project II: Key issue

As observed from the model introduced in Project I

An equation to define the resistance of a pipeline is required.

Fact:

The resistance of the pipeline
are based on current physical gas and pipeline properties

Literature reveals several methods for this purpose

Weymouth eq. (1912) (Osiadacz, 1987),
Panhandle A eq. (1940) and Panhandle B eq. (1956) (Crane, 1982).

Project II: Key issue

In this project, we also make use of

Weymouth equation:

where

$$x_{ij}^2 = W_{ij} (p_i^2 - p_j^2)$$

$$W_{ij} = \frac{d^5}{K g_i z_{ij} T f_{ij} L_{ij}}$$

Observations:

- W depends on z and g ;
 z depends also on g, p, T ;
- and g depends on upstream flows because of blending
based on the well from where the gas originates & degree of processing

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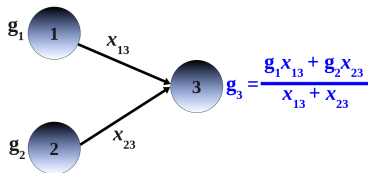
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Project II: Key statements

Then, what do we propose in this project?

Goal of the project

Extend previously suggested models to bring them closer to physical reality.

Accomplish by

Formulating a model where **not only x and p but g and z** are defined as state variables in a NG transmission system.

Focus on

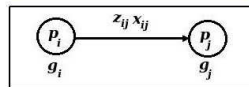
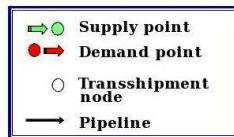
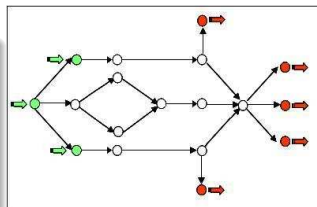
Flow maximization of natural gas transmission pipeline systems in steady-state.

Project II: Variability of g and z in pipeline systems

Notation

Decision variables:

- x_{ij} = flow through pipeline $(i,j) \in A$.
- p_i and p_j = upstream and downstream pressures in pipeline $(i,j) \in A$.
- g_i = gas specific gravity at node $i \in V$.
- z_{ij} = gas compressibility factor in pipeline $(i,j) \in A$.

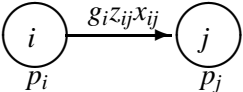


Project II: Modeling *the resistance of the pipeline*

1st key component of the model

By defining $w_{ij} = g_i z_{ij} W_{ij}$,

Weymouth eq. can be written as



$$g_i z_{ij} x_{ij}^2 = w_{ij} \left(p_i^2 - p_j^2 \right) \quad (1)$$

Thus, **(1)** is adopted in the model.

Project II: Balance of g in the system

2nd key component of the model

We assume that

$$\forall j \in V \setminus V_s, \quad g_j = \frac{\sum_{i \in V_j^-} g_i x_{ij}}{\sum_{i \in V_j^-} x_{ij}} \quad (2)$$

i.e., g of a blend of different gases is the weighted average of specific gravities of entering flows.

Project II: Balance of g in the system

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i.e., g of a blend of different gases is the weighted average of specific gravities of entering flows.

By multiplying **(2)** by the total entering flow:

$$g_j \sum_{i \in V_j^-} x_{ij} - \sum_{i \in V_j^-} g_i x_{ij} = 0, \forall j \in V \setminus V_s. \quad (3)$$

Thus, **(3)** is adopted in the model.

Project II: Compute z *in the pipeline*

3rd key component of the model

Literature suggests diverse methods to compute z

Experimental measurements, EoS methods (Dranchuk, 1975), empirical correlations (Katz et al., 1959) and regression analysis methods (Dranchuk, 1974; Gopal, 1977).

We have applied

The CNGA method:

$$z_{ij} = \frac{1}{1 + \frac{\bar{p}_{ij} \alpha 10^{\beta g_i}}{T^\delta}} \quad (4)$$

Assuming constant temperature

(4) can be written

$$z_{ij}(1 + \omega \bar{p}_{ij} \times 10^{\beta g_i}) = 1, \quad (5)$$

where $\omega = \frac{\alpha}{T^\delta}$ is an instance specific constant.

Project II: Compute z in the pipeline

3rd key component of the model

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Project II: Contributions

A more accurate NLP model for

Maximizing flow while considering the variability of g and z .

An extensive numerical experimentation:

- GAMS formulation for the NLP model.
 - Global optimizer: **BARON** (Tawarmalani & Sahinidis, 2004)
 - NLP local optimizer: **MINOS** (Murtaugh & Saunders, 1983)
 - Heuristic algorithm based on *an approximate model*

Through experiments, we have demonstrated that

- Neglecting g - and z - variation in instances where the variation is high, tends to give significantly misleading results.
- The proposed heuristic yields optimal or near-optimal solutions in most of the instances.

Project II: *Contributions*

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Project III: The line-packing problem

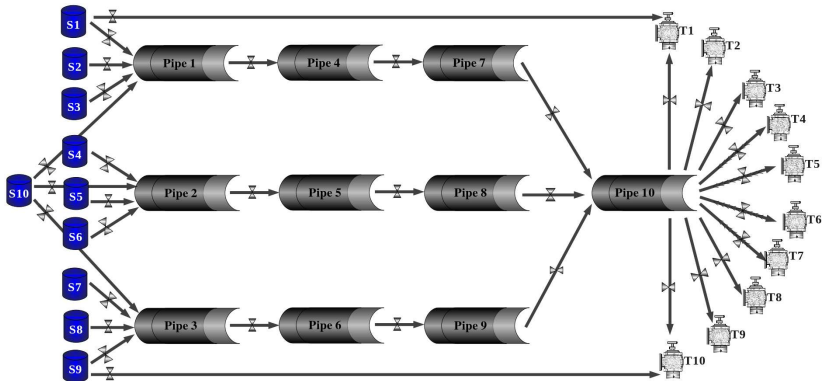
Finally, let's move to

PROJECT III

Project III: Problem statement

The optimization problem arises from one fact:

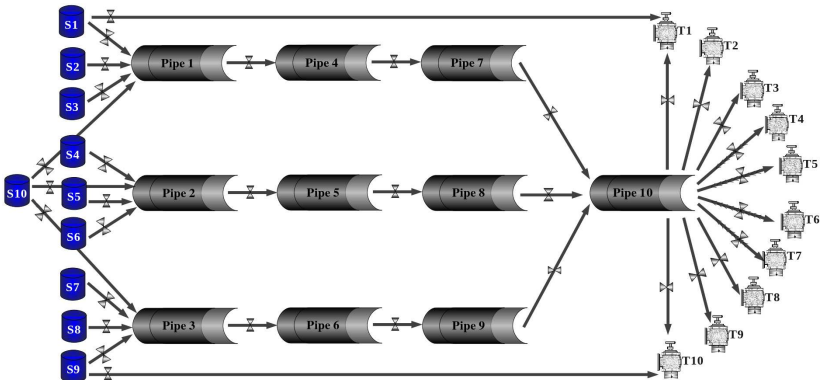
PIPELINES ARE
A means of gas transportation, BUT...



Project III: Problem statement

PIPELINES ALSO REPRESENT

POTENTIAL STORAGE UNITS FOR SAFETY STOCKS!



Project III: Key statements

Goal of the project

The efficient line-pack management as a strategy to meet market demand under scheduled events

Model:

Maximize total gas deliveries over a given planning horizon

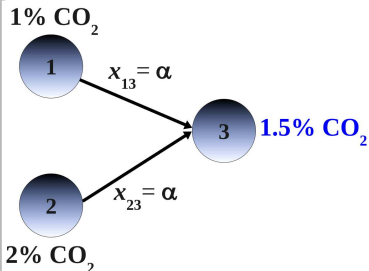
We thus need to

- ① optimize the refill of gas in pipelines in periods of sufficient capacity, and the withdrawals in periods of shortfall

Project III: Main ideas behind the model

Assumptions:

- Contracts specify upper bounds on, e.g., CO_2 content.
- CO_2 content is not equal at all sources.
- Flow into a pipeline = linear blend of entering flow streams
- Flow varies over time
- No blending inside the pipeline



Consequence:

A queue of batches with unequal CO_2 contents in the pipeline.

Project III: Conclusions on the project UiB

Contributions:

A MINLP model for the *line-packing problem* by
Building up batches to meet market demand over a given multi-period planning horizon

Observations from the numerical experiments:

- Test cases of moderate and small size were effectively handled by GO.

Concluding remarks UiB

After 3 wonderful years...



▲ **Project I:**

- 3 Papers published
- 4 Presentations:
Sweden, France,
Mexico & Norway

▲ **Project II:**

- 1 Paper submitted
- 2 Presentations:
Norway



Concluding remarks

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 - Denmark



And of course, **PhD thesis → Done!**

Thank you very much for listening...

UiB



END.

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